

DRAFT

1. Linear ODE Example - K.Makino

1.1. Preparation. Remainders:

$$\frac{d\vec{z}}{dt} = \vec{f}(\vec{z}, t), \quad \vec{z}(t) = \vec{z}(0) + \int_0^t \vec{f}(\vec{z}, t') dt'$$
$$\partial_i^{-1}(P_n + I^R) = \int_0^{x_i} P_{n-1} dx_i + \{B(P_n - P_{n-1}) + I^R\} \cdot B(x_i)$$

$$\sqrt{3} = 1.732050808\dots$$

$$\pi/6 = 0.523598775\dots$$

$$(\pi/6)^5 = 0.039354383\dots$$

$$\frac{1}{5!}(\pi/6)^5 = 3.279531944\dots \times 10^{-4}$$

$$\frac{1}{5!}(\pi/6)^6 = 1.717158911\dots \times 10^{-4}$$

$$\frac{1}{4!}(\pi/6)^4 = 3.13172232\dots \times 10^{-3}$$

$$\frac{1}{4!}(\pi/6)^5 = 1.639765972\dots \times 10^{-3}$$

The ODEs under consideration are

$$\frac{dx}{dt} = -y$$
$$\frac{dy}{dt} = x.$$

Taylor model identities can be expressed as

$$i_x = x_0 + [0, 0], \quad x_0 \in [-1, 1]$$

$$i_y = y_0 + [0, 0], \quad y_0 \in [-1, 1].$$

Let us consider the following initial conditions.

$$x(t=0) = 2 + i_x = 2 + x_0 + [0, 0]$$

$$y(t=0) = 0 + i_y = y_0 + [0, 0]$$

The following calculation is intended to show the procedures of the algorithms, and the numbers are not necessarily accurate.

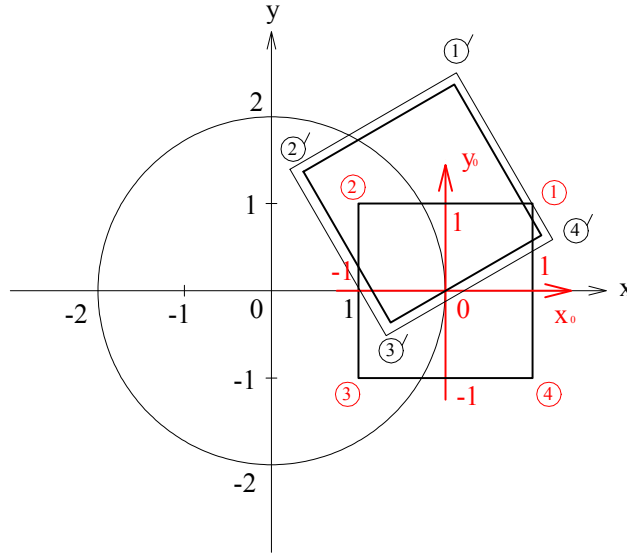
1.2. The First Time Step ($t = \pi/6$). The fixed point equations are

$$x(t) = x(t=0) + \int_0^t (-y(t)) dt = \mathcal{O}_x(\vec{z}(t))$$

$$y(t) = y(t=0) + \int_0^t (x(t)) dt = \mathcal{O}_y(\vec{z}(t)).$$

The procedures are

- Work on the polynomial part first.
- Find Taylor models satisfying the inclusion requirement.
 - Try $[0, 0]$.
 - Inflate by 2. (If necessary, repeat the inflation.)
- Refine Taylor models.



1.2.1. Polynomial Part. Fixed Point Iteration: Step 1

$$x(t) = 2 + x_0 + \int_0^t [-y_0] dt = 2 + x_0 - y_0 t$$

$$y(t) = y_0 + \int_0^t [2 + x_0] dt = y_0 + (2 + x_0)t$$

Fixed Point Iteration: Step 2

$$x(t) = 2 + x_0 + \int_0^t [-y_0 - (2 + x_0)t] dt = 2 + x_0 - y_0 t - (2 + x_0) \frac{t^2}{2}$$

$$y(t) = y_0 + \int_0^t [2 + x_0 - y_0 t] dt = y_0 + (2 + x_0)t - y_0 \frac{t^2}{2}$$

Fixed Point Iteration: Step ...

Fixed Point Iteration: Step 5

$$x(t) = 2 + x_0 - y_0 t - (2 + x_0) \frac{t^2}{2} + y_0 \frac{t^3}{3!} + (2 + x_0) \frac{t^4}{4!} - y_0 \frac{t^5}{5!}$$

$$y(t) = y_0 + (2 + x_0)t - y_0 \frac{t^2}{2} - (2 + x_0) \frac{t^3}{3!} + y_0 \frac{t^4}{4!} + (2 + x_0) \frac{t^5}{5!}$$

Remark: $\vec{z}(t)$ of a linear system has the linear dependence on the initial condition \vec{z}_0 . $\vec{z}(t)$ of a nonlinear system has the nonlinear dependence on \vec{z}_0 . For example, the Volterra equations, $dx/dt = 2x(1 - y)$, $dy/dt = -y(1 - x)$, have the nonlinear dependence on x_0 and y_0 , which is not just the second order dependence, but the high order dependence.

Thus, for the fifth order computation, we obtain the fifth order polynomial depending on time t and the initial condition \vec{z}_0 as a result of the fixed point iteration.

$$(1.1) \quad \begin{aligned} P_x(x_0, y_0, t) &= 2 + x_0 - y_0 t - (2 + x_0) \frac{t^2}{2} + y_0 \frac{t^3}{3!} + (2 + x_0) \frac{t^4}{4!} \\ P_y(x_0, y_0, t) &= y_0 + (2 + x_0)t - y_0 \frac{t^2}{2} - (2 + x_0) \frac{t^3}{3!} + y_0 \frac{t^4}{4!} + 2 \frac{t^5}{5!} \end{aligned}$$

1.2.2. *Self Inclusion Finding Process.* We apply the Picard operation to

$$\begin{aligned} x(t) &= P_x(x_0, y_0, t) + [0, 0] \\ y(t) &= P_y(x_0, y_0, t) + [0, 0] \end{aligned}$$

using the polynomial solution part (1.1).

$$\begin{aligned} x(t) &= 2 + x_0 + \int_0^t [-y(t)] dt \\ &= P_x(x_0, y_0, t) + \left\{ B \left(-y_0 \frac{t^4}{4!} + 2 \frac{t^5}{5!} \right) + [0, 0] \right\} \cdot B(t) \\ &= P_x(x_0, y_0, t) + I_x^{(0)} \\ y(t) &= P_y(x_0, y_0, t) + \left\{ B \left(x_0 \frac{t^4}{4!} \right) + [0, 0] \right\} \cdot B(t) \\ &= P_y(x_0, y_0, t) + I_y^{(0)} \end{aligned}$$

and we have

$$\begin{aligned} I_x^{(0)} &= [-1.99 \times 10^{-3}, 1.64 \times 10^{-3}] \\ I_y^{(0)} &= [-1.64 \times 10^{-3}, 1.64 \times 10^{-3}]. \end{aligned}$$

This provides the guideline to find a self including solution. We inflate it by 2 repeatedly until it satisfies the self inclusion condition.

$$\begin{aligned} I_x^{(1)} &= 2 \cdot I_x^{(0)} = [-3.97 \times 10^{-3}, 3.28 \times 10^{-3}] \\ I_y^{(1)} &= 2 \cdot I_y^{(0)} = [-3.28 \times 10^{-3}, 3.28 \times 10^{-3}]. \end{aligned}$$

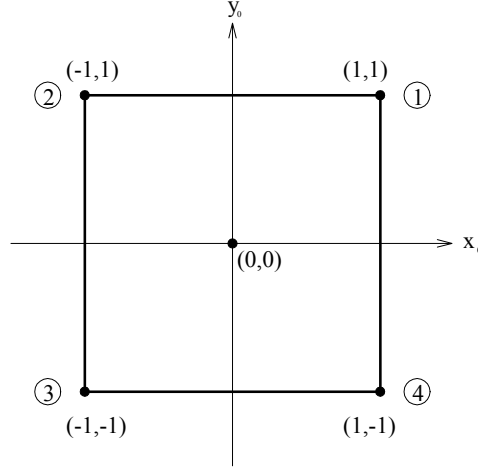
Applying the Picard operation, we obtain

$$\begin{aligned} I_x^{(1)*} &= [-3.71 \times 10^{-3}, 3.36 \times 10^{-3}] \\ I_y^{(1)*} &= [-3.72 \times 10^{-3}, 3.36 \times 10^{-3}]. \end{aligned}$$

$$\begin{aligned} I_x^{(2)} &= 2^2 \cdot I_x^{(0)} = [-7.94 \times 10^{-3}, 6.56 \times 10^{-3}] \\ I_y^{(2)} &= 2^2 \cdot I_y^{(0)} = [-6.56 \times 10^{-3}, 6.56 \times 10^{-3}]. \end{aligned}$$

$$\begin{aligned} I_x^{(2)*} &= [-5.42 \times 10^{-3}, 5.08 \times 10^{-3}] \\ I_y^{(2)*} &= [-5.80 \times 10^{-3}, 5.08 \times 10^{-3}]. \end{aligned}$$

Thus, we found a self including solution $\vec{P} + \vec{I}^{(2)*}$.



1.2.3. *Refinement Process.* Now, we apply the Picard operation repeatedly until the desired sharpness of enclosure is achieved.

$$\vec{P} + \vec{I}_1 = \mathcal{O} \left(\vec{P} + \vec{I}^{(2)*} \right) = \begin{pmatrix} [-4.64 \times 10^{-3}, 4.68 \times 10^{-3}] \\ [-4.48 \times 10^{-3}, 4.30 \times 10^{-3}] \end{pmatrix}$$

$$\vec{P} + \vec{I}_2 = \mathcal{O} \left(\vec{P} + \vec{I}_1 \right) = \begin{pmatrix} [-4.24 \times 10^{-3}, 3.99 \times 10^{-3}] \\ [-4.07 \times 10^{-3}, 4.09 \times 10^{-3}] \end{pmatrix}$$

Continuing until the relative tolerance of 1% is met,

$$\vec{P} + \vec{I}_7 = \mathcal{O} \left(\vec{P} + \vec{I}_6 \right) = \begin{pmatrix} [-3.84 \times 10^{-3}, 3.57 \times 10^{-3}] \\ [-3.66 \times 10^{-3}, 3.52 \times 10^{-3}] \end{pmatrix}.$$

1.2.4. *Taylor Model Solution at $t = \pi/6$.*

$$\begin{aligned} x(t = \pi/6) &= P_x(x_0, y_0, t = \pi/6) + [-3.84 \times 10^{-3}, 3.57 \times 10^{-3}] \\ &= 1.732 + 0.866x_0 - 0.500y_0 + [-3.84 \times 10^{-3}, 3.57 \times 10^{-3}] \\ y(t = \pi/6) &= P_y(x_0, y_0, t = \pi/6) + [-3.66 \times 10^{-3}, 3.52 \times 10^{-3}] \\ (1.2) \quad &= 1.000 + 0.500x_0 + 0.866y_0 + [-3.66 \times 10^{-3}, 3.52 \times 10^{-3}] \end{aligned}$$

Initial position (x_0, y_0) at $t = 0$	Mapped position (P_x, P_y) at $t = \pi/6$
(0,0)	(1.732,1.000)
(1,1)	(2.098,2.366)
(-1,1)	(0.366,1.366)
(-1,-1)	(1.366,-0.366)
(1,-1)	(3.098,0.634)

1.3. **Taylor Model Solution at the Second Time Step ($t = 2 \times \pi/6$).**

$$\begin{aligned} x(t = \pi/3) &= 1.000 + 0.500x_0 - 0.866y_0 + [-1.29 \times 10^{-2}, 1.26 \times 10^{-2}] \\ y(t = \pi/3) &= 1.732 + 0.866x_0 + 0.500y_0 + [-1.28 \times 10^{-2}, 1.24 \times 10^{-2}] \end{aligned}$$

1.4. Taylor Model Solution at the Third Time Step ($t = 3 \times \pi/6$).

$$x(t = \pi/2) = -1.000y_0 + [-3.17 \times 10^{-2}, 3.16 \times 10^{-2}]$$

$$y(t = \pi/2) = 2.000 + 1.000x_0 + [-3.20 \times 10^{-2}, 3.12 \times 10^{-2}]$$

1.5. Shrink Wrapping. This is to illustrate the method of shrink wrapping, and we use the solution Taylor models at the first time step $t = \pi/6$. For the simplicity of the argument, we will use \sin , \cos and so on. From eq. (1.2),

$$x(t = \pi/6) = \sqrt{3} + \cos \pi/6 \cdot x_0 - \sin \pi/6 \cdot y_0 + I_x^R$$

$$y(t = \pi/6) = 1 + \sin \pi/6 \cdot x_0 + \cos \pi/6 \cdot y_0 + I_y^R$$

$$\mathcal{M}(\vec{z}) = M(\vec{z}) = \hat{A} \cdot \vec{z} + \vec{a}$$

where

$$\hat{A} = \begin{pmatrix} \cos \pi/6 & -\sin \pi/6 \\ \sin \pi/6 & \cos \pi/6 \end{pmatrix}, \quad \vec{a} = \begin{pmatrix} \sqrt{3} \\ 1 \end{pmatrix}, \quad \hat{A}^{-1} = \begin{pmatrix} \cos \pi/6 & \sin \pi/6 \\ -\sin \pi/6 & \cos \pi/6 \end{pmatrix}$$

so

$$M^{-1}(\vec{z}) = \hat{A}^{-1} \cdot (\vec{z} - \vec{a})$$

Thus

$$\begin{aligned} M^{-1} \circ (\mathcal{M}(\vec{z}_0) + \vec{I}^R) &= M^{-1} \circ (M(\vec{z}_0) + \vec{I}^R) = \hat{A}^{-1} \cdot (\hat{A} \cdot \vec{z}_0 + \vec{a} + \vec{I}^R - \vec{a}) \\ &= \vec{z}_0 + \hat{A}^{-1} \cdot \vec{I}^R = \vec{z}_0 + \begin{pmatrix} \cos \pi/6 & \sin \pi/6 \\ -\sin \pi/6 & \cos \pi/6 \end{pmatrix} \begin{pmatrix} I_x^R \\ I_y^R \end{pmatrix} \\ &= \vec{z}_0 + \begin{pmatrix} 0.866 & 0.500 \\ -0.500 & 0.866 \end{pmatrix} \begin{pmatrix} [-3.84 \times 10^{-3}, 3.57 \times 10^{-3}] \\ [-3.66 \times 10^{-3}, 3.52 \times 10^{-3}] \end{pmatrix} \\ &= \vec{z}_0 + \begin{pmatrix} [-5.16 \times 10^{-3}, 4.86 \times 10^{-3}] \\ [-4.96 \times 10^{-3}, 4.97 \times 10^{-3}] \end{pmatrix} \\ &\left(\begin{pmatrix} [-5.16 \times 10^{-3}, 4.86 \times 10^{-3}] \\ [-4.96 \times 10^{-3}, 4.97 \times 10^{-3}] \end{pmatrix} \subseteq 5.16 \times 10^{-3} \cdot \begin{pmatrix} [-1, 1] \\ [-1, 1] \end{pmatrix} \right) \equiv d \begin{pmatrix} [-1, 1] \\ [-1, 1] \end{pmatrix}. \end{aligned}$$

So, $d = 5.16 \times 10^{-3}$. The map with shrink wrapping is

$$\begin{aligned} \mathcal{M}^{\text{SW}}(\vec{z}_0) &= \hat{A}(1 + d)\vec{z}_0 + \vec{a} \\ &= (1 + 5.16 \times 10^{-3}) \begin{pmatrix} 0.866 & -0.500 \\ 0.500 & 0.866 \end{pmatrix} \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} + \begin{pmatrix} 1.732 \\ 1.000 \end{pmatrix}. \end{aligned}$$