

# Rigorous Classification of Manifold Tangles and Bounds for Entropy

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## TM-enclosure of invariant manifolds

Local polynomial approximation

Heuristic verification with remainder bounds

Global manifolds by iteration

## Computer-assisted picture verification for entropy estimates

Choice of rectangles

Verified mapping

## Automatic determination of symbolic dynamics

Construction of rectangles

Setup of incidence matrix

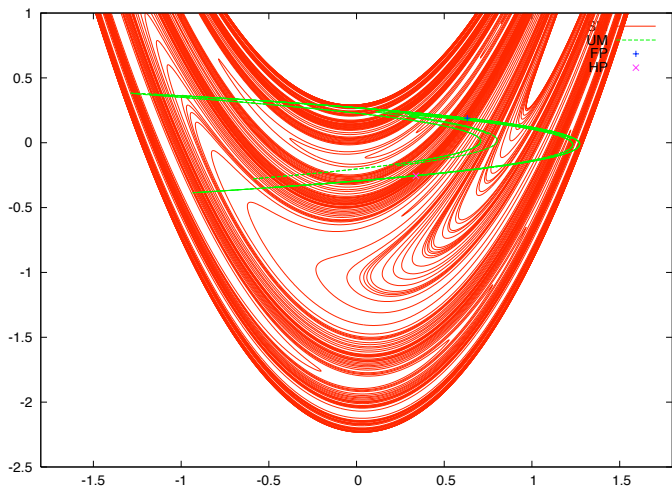
In the further discussion, we consider the Henon map

$$\mathcal{H}(x, y) = \mathcal{H}_{a,b}(x, y) = \begin{pmatrix} 1 + y - a \cdot x^2 \\ b \cdot x \end{pmatrix}$$

- ▶ it has a hyperbolic fixed point at  $\approx (0.63135, 0.18940)$
- ▶ it has a hyperbolic fixed point at  $\approx (0.33885, -0.25511)$
- ▶ the determinant of the Jacobian is  $-b$

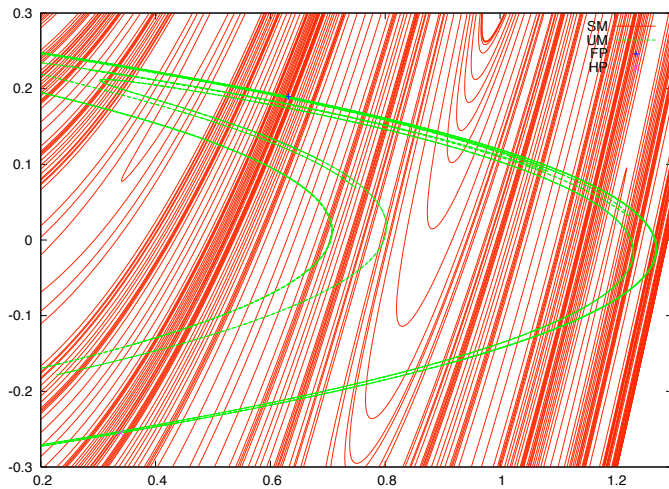
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└ TM-enclosure of invariant manifolds



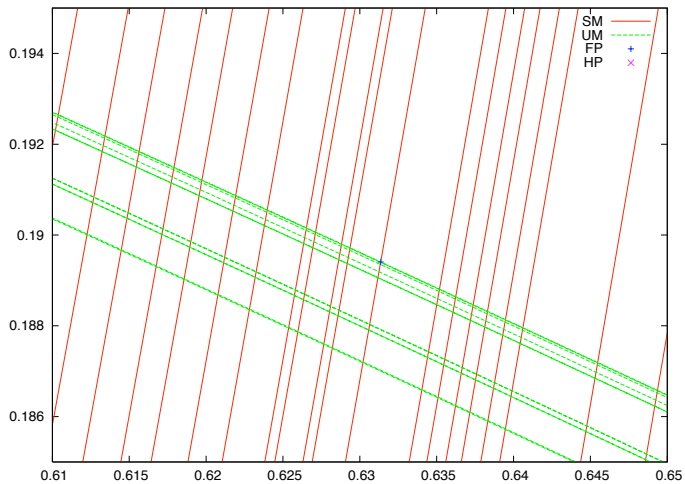
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### Strategy:

- ▶ find nonverified polynomial approximation of local manifolds near hyperbolic fixed point, using DA
- ▶ heuristically outfit polynomial with remainder bounds to obtain a TM-enclosure of the local manifold
- ▶ obtain enclosures of significant parts of the global manifolds as iterated images/preimages of the local manifold enclosures

Various techniques exist to obtain local polynomial parametrizations of manifold.

# 1. Hubbard's method (for planar systems)

- ▶ consider a hyperbolic fixed point  $x_0$
- ▶ let  $v_u, v_s$  be the eigenvectors to the un/stable eigenvalues  $\lambda_u$  and  $\lambda_s$  at  $x_0$
- ▶ consider test functions

$$\gamma_n^u(t) := \mathcal{H}^n(x_0 + \frac{t}{\lambda_u^n}) \cdot v_u$$
$$\gamma_n^s(t) := \mathcal{H}^{-n}(x_0 + t \cdot \lambda_s^n) \cdot v_s$$

- ▶ Thm.(Hubbard): the functions  $\gamma_n^u$  and  $\gamma_n^s$  converge uniformly on compact sets to the true unstable manifolds  $W^u$  and  $W^s$  around  $x_0$



## 2. Complete normal form transformation

Under certain nonresonance assumptions, perform a NFT of  $\mathcal{H}$  around  $x_0$ , s.t. in new coordinates  $\mathcal{H}$  is fully linearized.

- ▶ find the NFT  $\psi$  s.t.  $\psi^{-1} \circ \mathcal{H} \circ \psi(x) = \begin{pmatrix} \lambda_u & 0 \\ 0 & \lambda_s \end{pmatrix} \cdot \begin{pmatrix} x \\ y \end{pmatrix}$
- ▶ in this picture,  $W_{NFT}^u = \mathbb{R} \times 0$  and  $W_{NFT}^s = 0 \times \mathbb{R}$
- ▶ obtain  $W^u = \psi(W_{NFT}^u)$  and  $W^s = \psi(W_{NFT}^s)$  in original coordinates

## Invariant Manifold Enclosure Theorem

Let  $P = (P_1, P_2)$  be a two-dimensional bijective polynomial on  $U$  which satisfies  $P(0, 0) = (0, 0)$ . Let  $(\tilde{P}, \tilde{I}) := \mathcal{H}(P, I)$  evaluated in Taylor model arithmetic, where  $I$  is the trivial interval  $[0, 0]^2$ . Let

$$\begin{aligned} R &= P(U), \tilde{R} = \tilde{P}(U) + \tilde{I}, \text{ and} \\ B_u &= P([-1, 1] \times [1, 1]), B_l = P([-1, 1] \times [-1, -1]) \end{aligned}$$

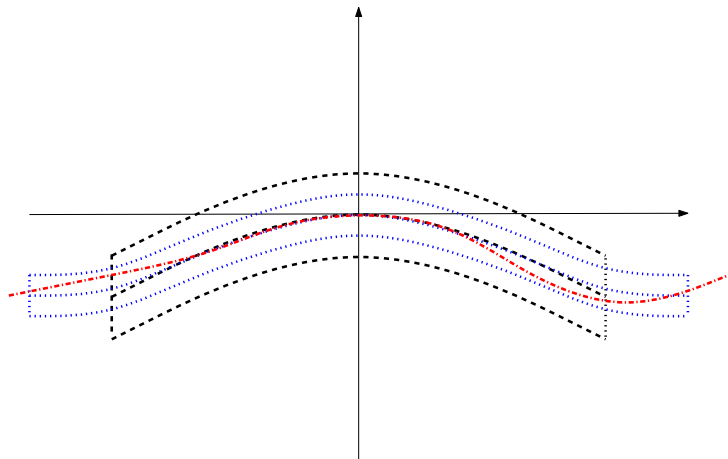
denote the ranges of  $P$  and  $\tilde{P} + \tilde{I}$  and the 'upper' and 'lower' boundaries of the range  $R$ , respectively. Assume now that

$$(B_u \cup B_l) \cap \tilde{R} = \emptyset. \quad (1)$$

Then the unstable manifold does not leave  $R$  through  $B_u$  or  $B_l$ .

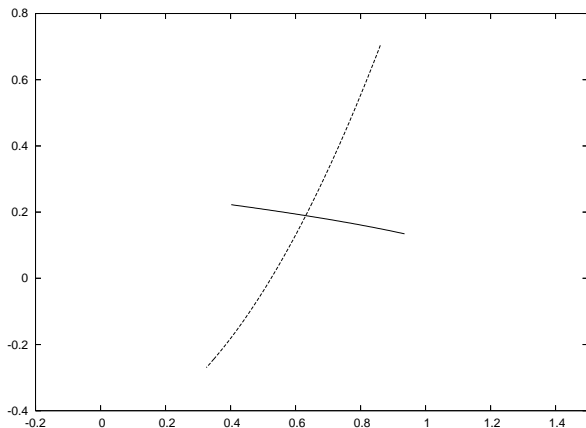
- └ TM-enclosure of invariant manifolds
- └ Heuristic verification with remainder bounds

## TM-enclosure of local manifold



- └ TM-enclosure of invariant manifolds
- └ Heuristic verification with remainder bounds

## Local manifolds for the standard Hénon map



General idea: TM-enclosure of local manifold will iteratively yield TM-enclosure of global manifolds, if images/preimages are computed in TM-arithmetic.

In practice, there are problems:

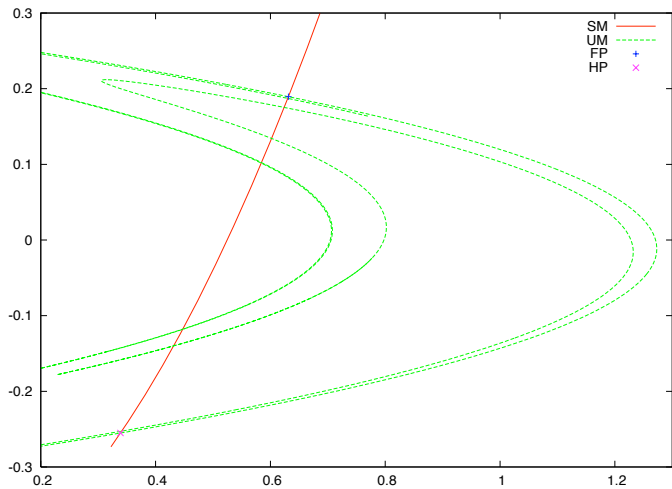
- ▶ blow-up of remainder bounds through strong length-growth of curves
- ▶ blow-up of remainder bound because manifolds take 'sharp turns'  $\implies$  challenging polynomial approximation
- ▶ blow-up of remainder bounds through strong expansion (Lipschitz constant of maps)

Solution step-size control/dynamic domain decomposition  $\implies$  'chopping' of TM-tubes

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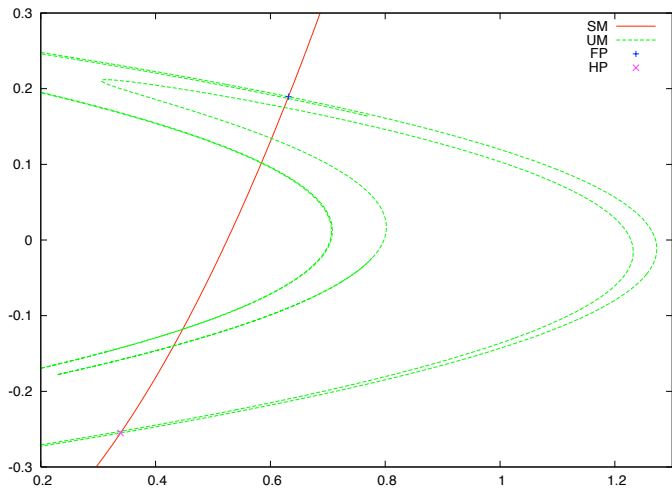
- └ Global manifolds by iteration



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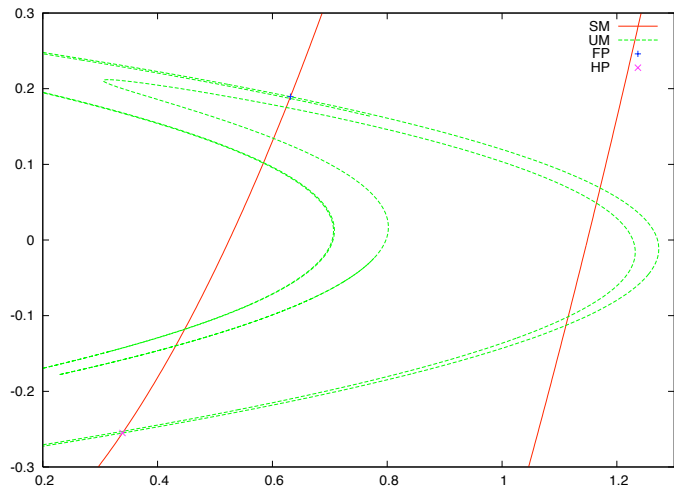
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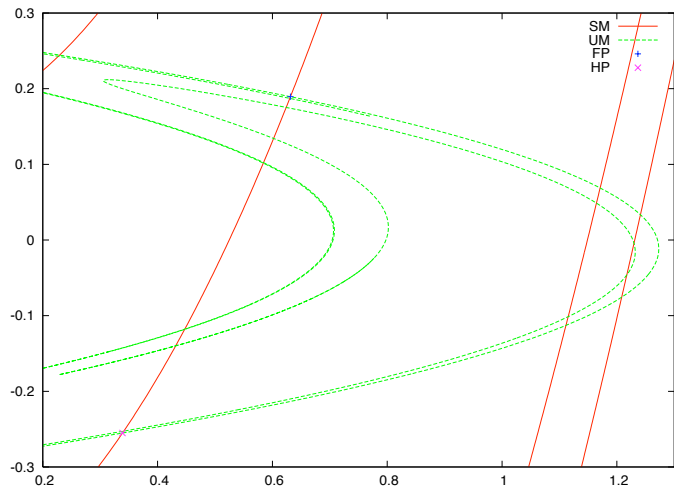




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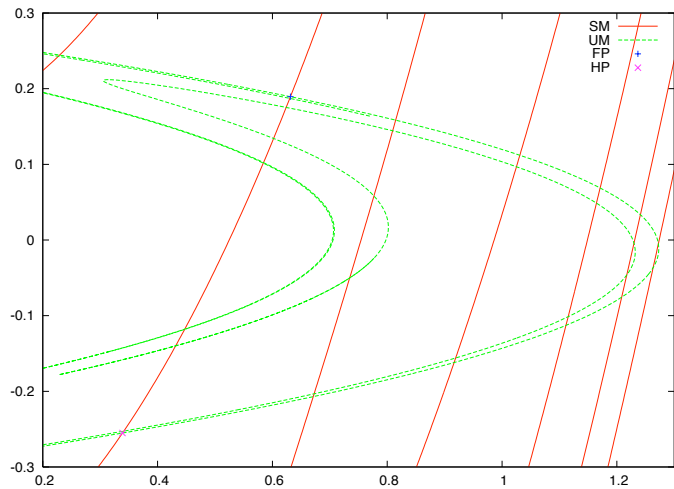
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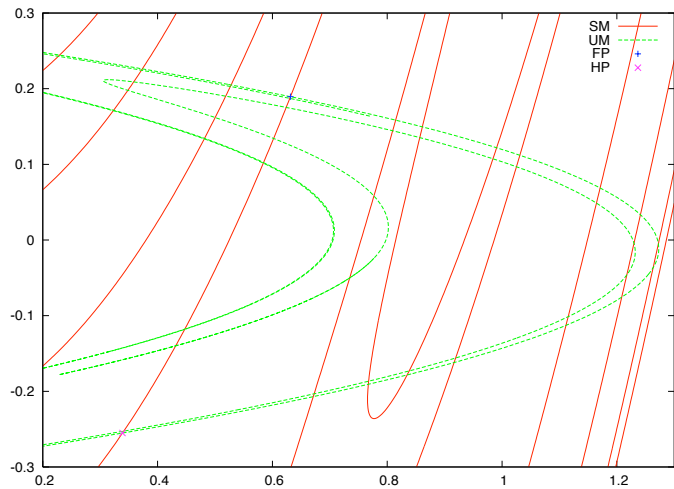
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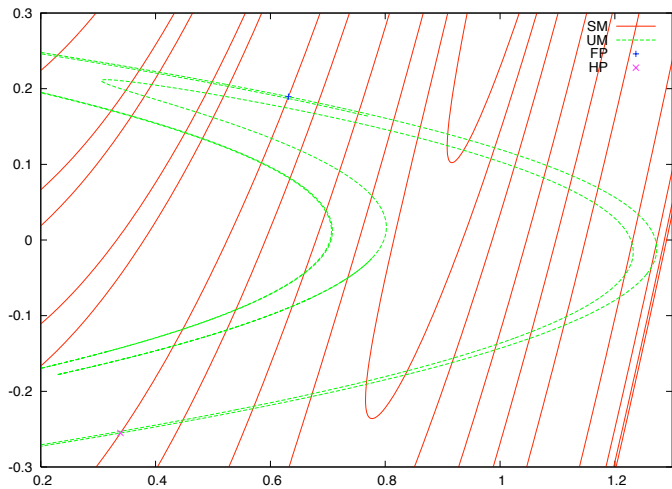
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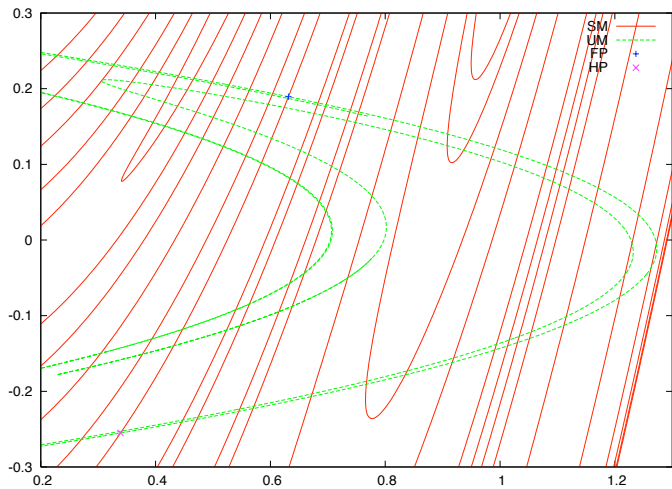
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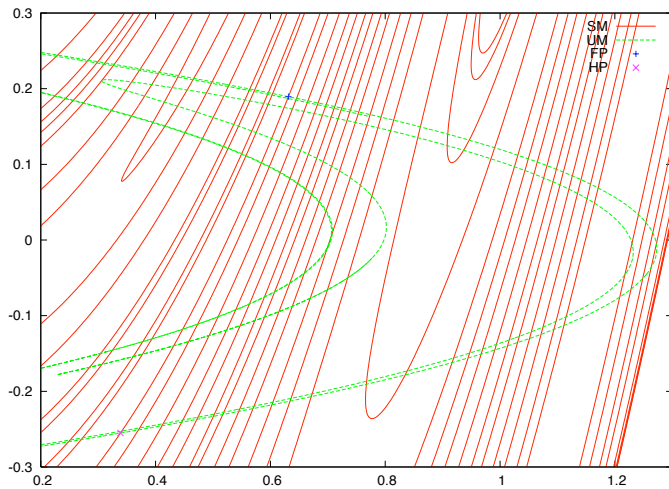
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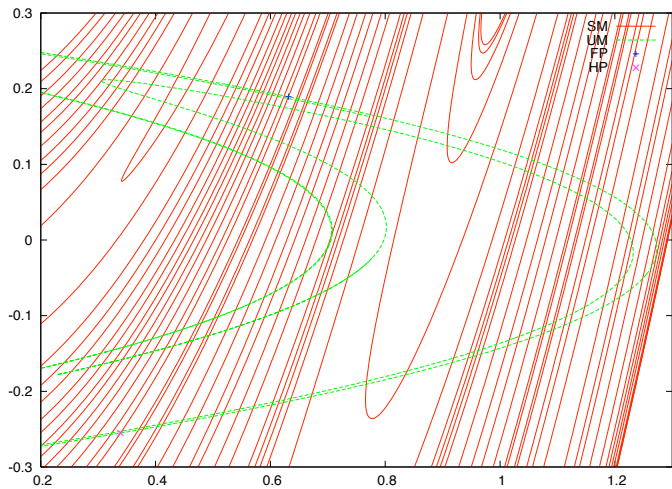
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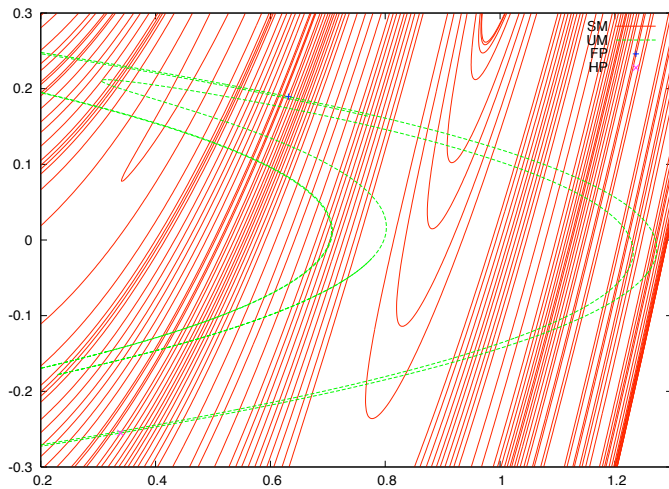
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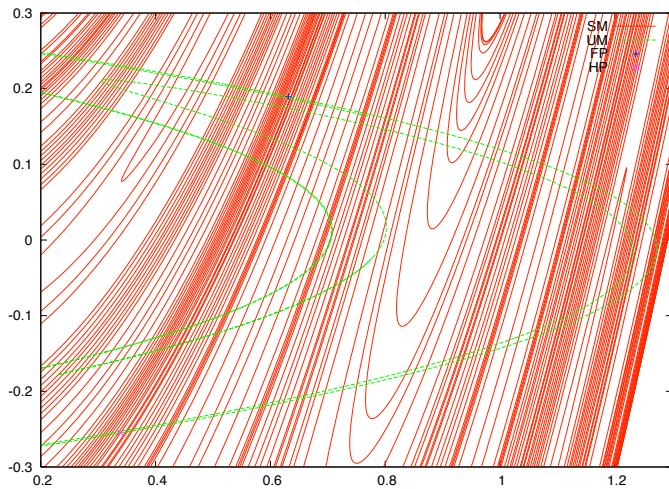




# Rigorous Classification of Manifold Tangles and Bounds for Entropy

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## Topological entropy

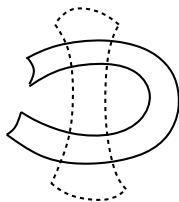
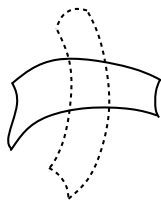
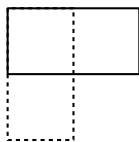
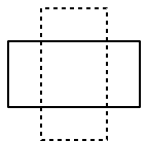
**Def.:** Let  $(X, d)$  be a compact metric space and  $f : X \rightarrow X$  a continuous self-map. Then

$$h_{top}(f) := \lim_{\epsilon \rightarrow 0} \limsup_{n \rightarrow \infty} \frac{1}{n} \log r(\epsilon, n)$$

- ▶ dynamical invariant
- ▶ if  $> 0$ , chaotic dynamics
- ▶ exponential length growth of curves

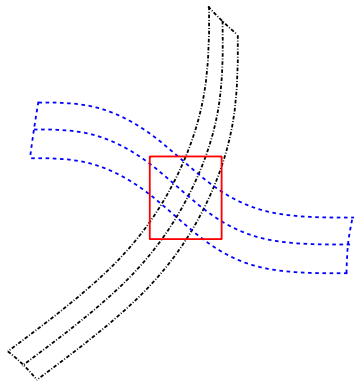
- ▶ We wish to compute lower bounds of the topological entropy  $h_{\mathcal{H}}$  of the Henon map  $\mathcal{H} = \mathcal{H}_{a,b}$
- ▶ find symbolic dynamics by considering regions (curvilinear rectangles)  $R_j$  that overlap each other under iteration
- ▶ compute incidence matrix  $A$  for rectangles that Markov-cross:  
 $A_{ij} := 1$  iff  $\mathcal{H}_{a,b}(R_i) \cap R_j$  Markov,  $A_{i,j} := 0$  else
- ▶ compute lower bound for  $h_{\mathcal{H}}$  as the log of the largest real eigenvalue of  $A$

## Markov crossings



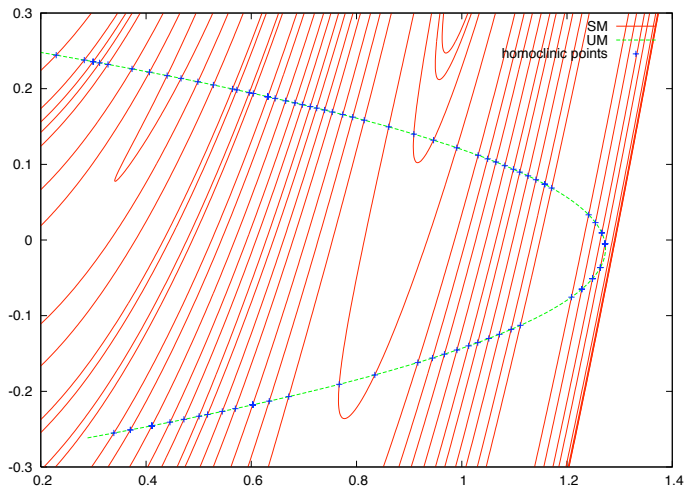
- └ Automatic determination of symbolic dynamics
- └ Construction of rectangles

## Homoclinic point enclosure



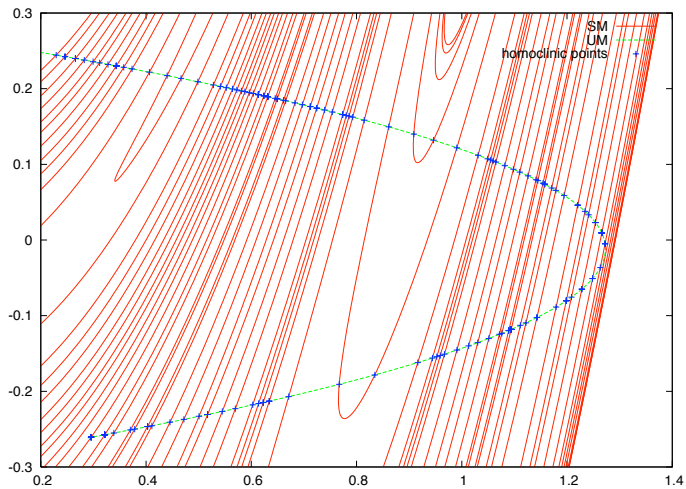
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- └ Automatic determination of symbolic dynamics
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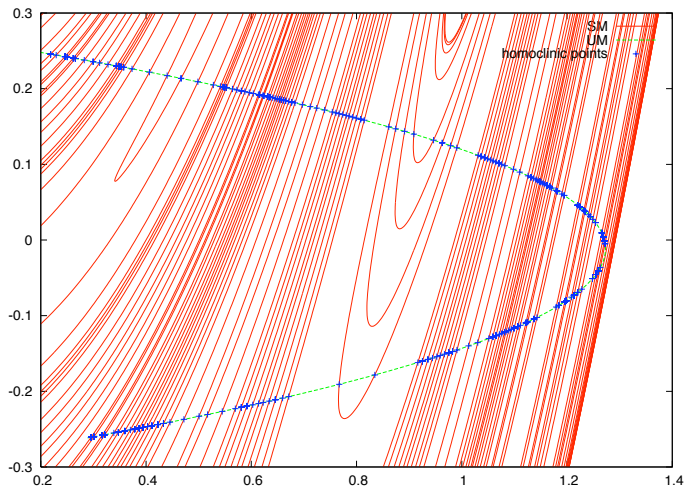
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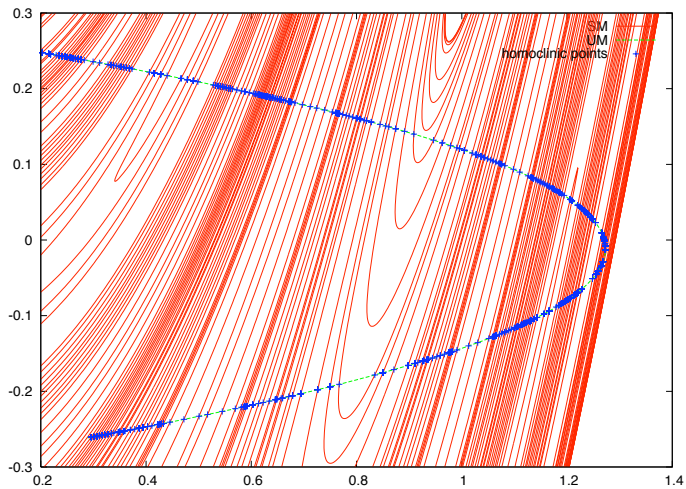




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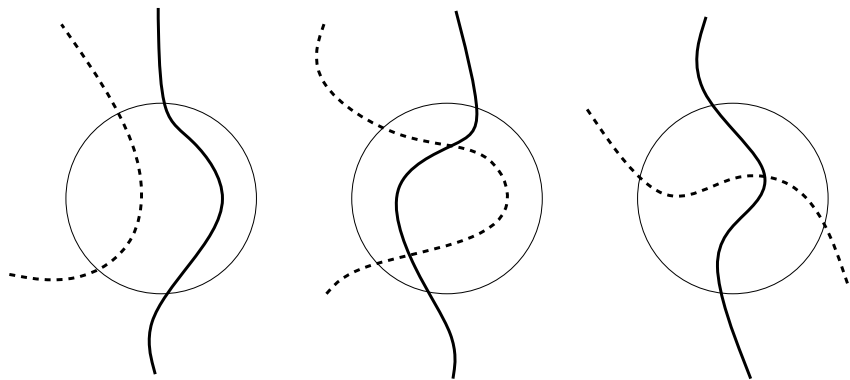


Some subtle intricacies connected to the homoclinic point search:

- ▶ the accuracy of the GO is limited. We can resolve boxes of size  $10^{-5}$  in the parameter space, hence we get box enclosures of the HPs in phase space of size much bigger than the remainder bounds. We want box enclosures of the HPs not significantly bigger than the remainder bounds
- ▶ we will not only pick up transverse HPs, but also homoclinic tangencies or near-tangencies
- ▶ we cannot guarantee that there is one and only one transverse HP in the box

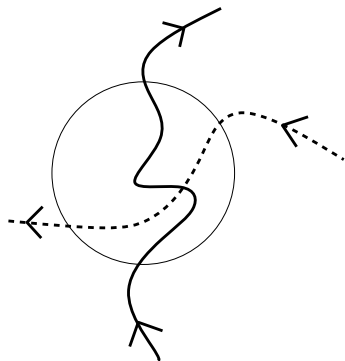
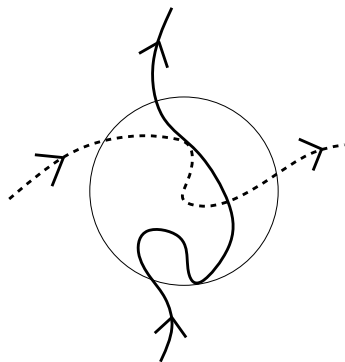
- └ Automatic determination of symbolic dynamics
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## Verification of existence of homoclinic point



- └ Automatic determination of symbolic dynamics
- └ Construction of rectangles

## Crossing orientation



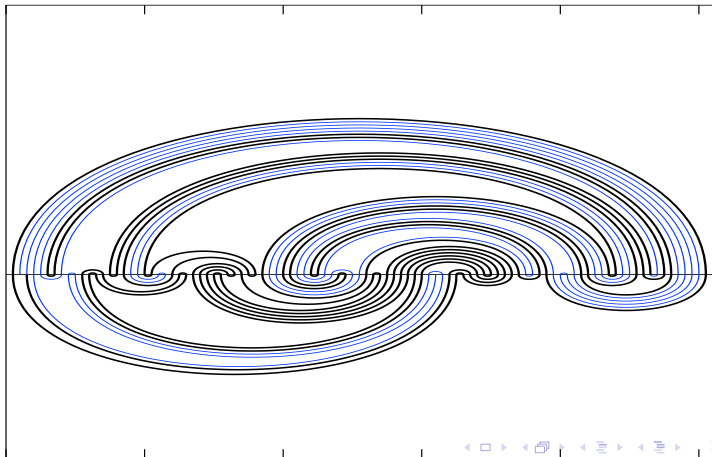
We have found the sets of homoclinic points. Additionally, we can find

- ▶ their order along both stable and unstable manifold
- ▶ their 'orientation' (tangent vectors to manifolds at the homoclinic points)
- ▶ how they map into each other (image-preimage-pairs of HPs):  
 consider  $UM \cap SM = \{p_1, \dots, p_n\}$ , and  
 $\mathcal{H}(UM) \cap SM = \{q_1, \dots, q_k\}$ . Then  $\{p_1, \dots, p_n\} \subset \{q_1, \dots, q_k\}$   
 and  $\forall n \exists k(n)$  s.t.  $\mathcal{H}(p_n) = q_{k(n)}$

This info will enable us to automatically construct curvilinear rectangles with boundaries in the un/stable mfd. and homoclinic points as cornerpoints.

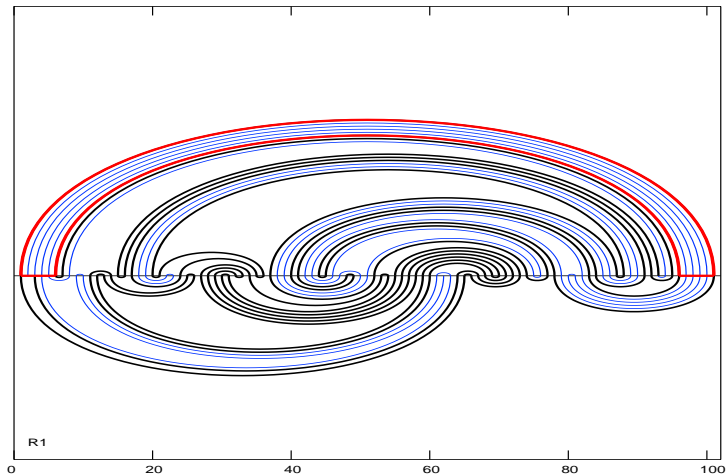
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## Untangled attractor



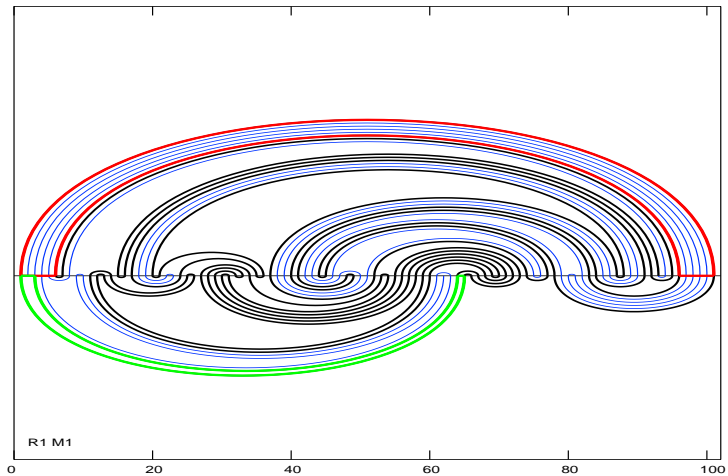
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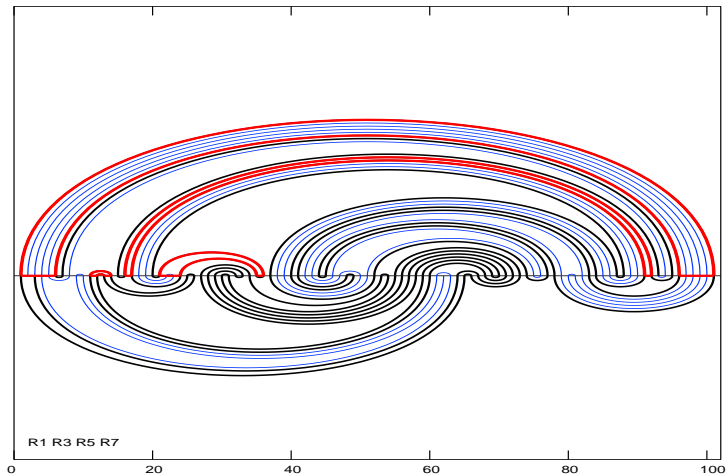
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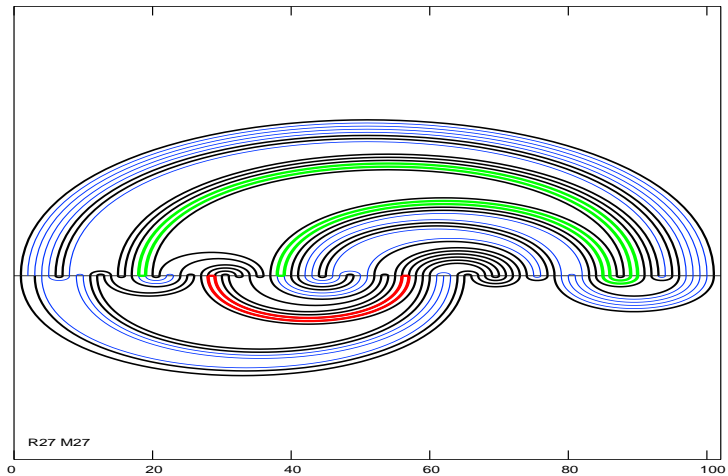
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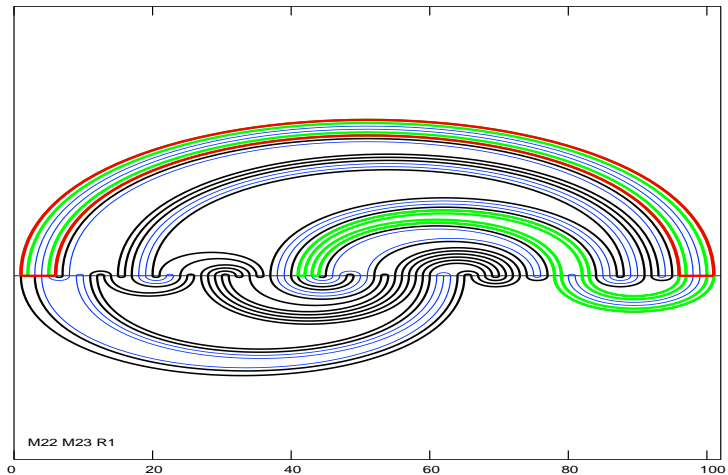
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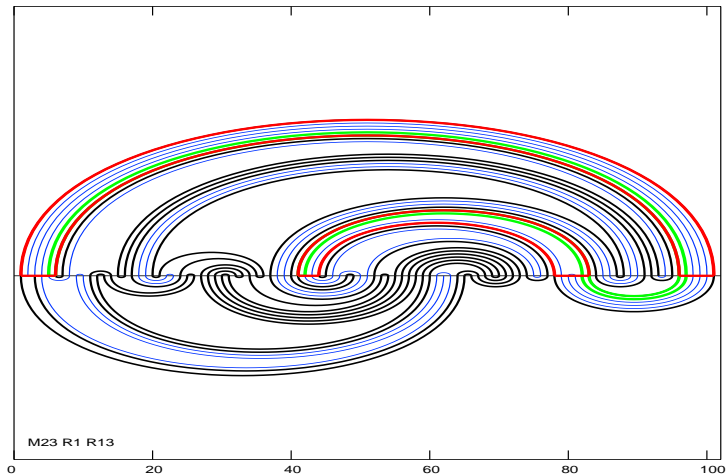
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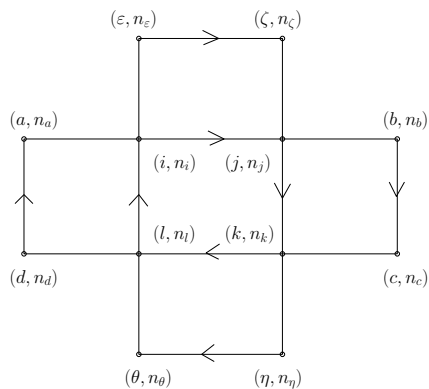
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- └ Automatic determination of symbolic dynamics
- └ Construction of rectangles



- └ Automatic determination of symbolic dynamics
- └ Setup of incidence matrix

## Determination of Markov crossings



## Lower entropy bounds

- ▶ 161 HPs, 66 symbols, 94 crossings  $\implies h_{top} \geq 0.4309$
- ▶ 267 HPs, 130 symbols, 205 crossings  $\implies h_{top} \geq 0.4402$
- ▶ 427 HPs, 229 symbols, 366 crossings  $\implies h_{top} \geq 0.4499$
- ▶ 707 HPs, 392 symbols, 621 crossings  $\implies h_{top} \geq 0.4536$

## Summary

- ▶ accurate polynomial approximations of local invariant manifolds can be heuristically and sharply verified with Taylor models
- ▶ significant pieces of the global manifold structure can be obtained through verified iteration schemes
- ▶ all homo-/heteroclinic intersections can be computed with comparable accuracy via verified global optimization
- ▶ HPs are ordered and have 'orientation'
- ▶ mapping properties in the set of HPs can be obtained, leads to construction of symbolic dynamics with hundreds of symbols, entropy estimates etc.

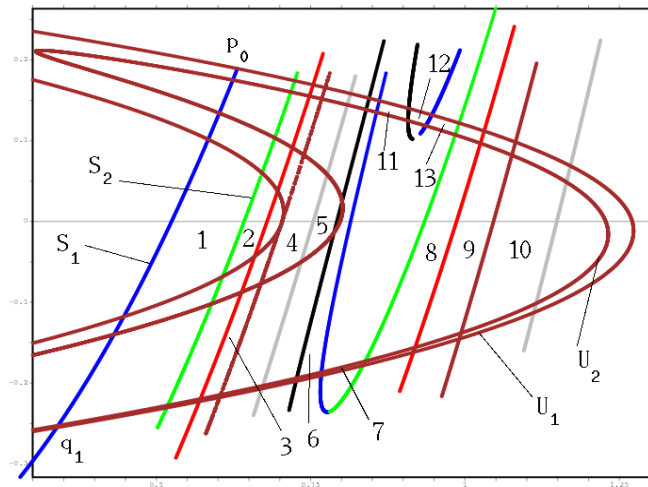
## Outlook

- ▶ improvement in speed and user convenience
- ▶ arbitrary precision Taylor model arithmetic  $\implies$  higher resolution of HPs  $\implies$  much larger number of HPs and finer dynamics
- ▶ application to new systems: Different parameters for Hénon (area-preserving case), forced oscillations, invariant manifolds on Poincaré sections etc.
- ▶ suggestions are welcome



- └ Automatic determination of symbolic dynamics
- └ Setup of incidence matrix

## S. Newhouse choice of rectangles



## Entropy result (S. Newhouse)

The 13 rectangles and mappings yield the incidence matrix:

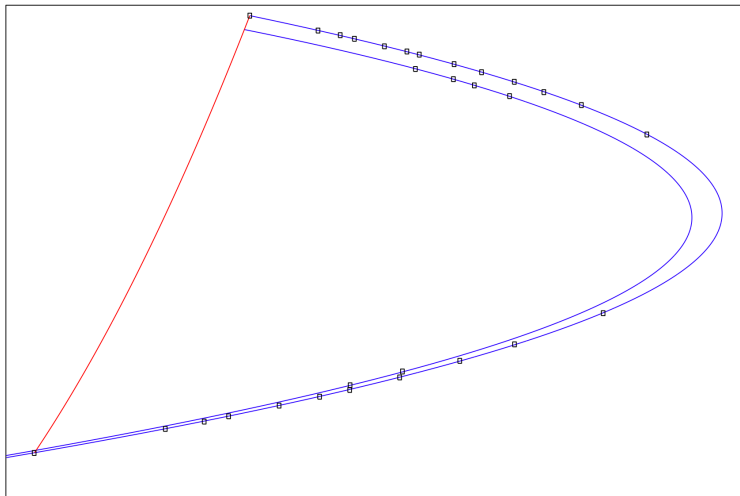
$$A = \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 & \cdot & \cdot & \cdot & \cdot & 1 & 1 & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & 1 & \cdot & \cdot & \cdot & 1 \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & 1 & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & 1 & \cdot & \cdot \\ 1 & 1 & 2 & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ 1 & 1 & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ 2 & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ 2 & 2 & 2 & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & 1 & 1 & \cdot & \cdot \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & \cdot & \cdot & \cdot & \cdot & \cdot \\ 2 & 2 & 2 & 2 & 2 & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ 2 & 2 & 2 & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ 2 & 2 & 2 & 2 & 2 & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \end{pmatrix}$$

**Theorem:** The standard Henon map has the top. entropy

$$h_{top}(\mathcal{H}) \geq 0.46469$$

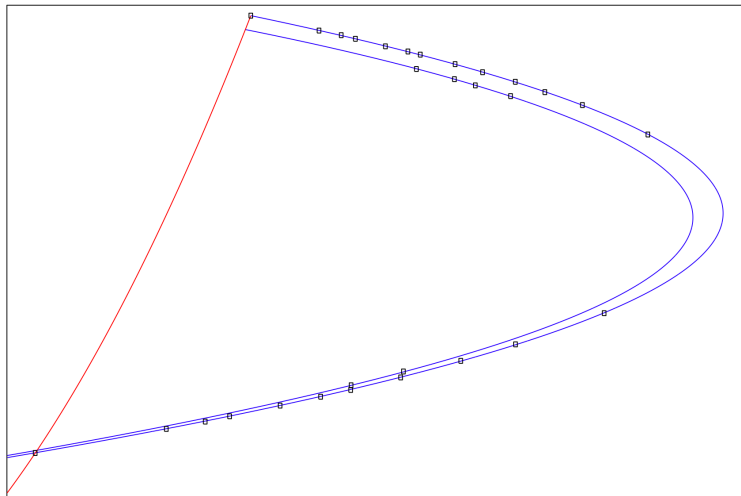
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$$\mathcal{H}^{-0}(S_1)$$



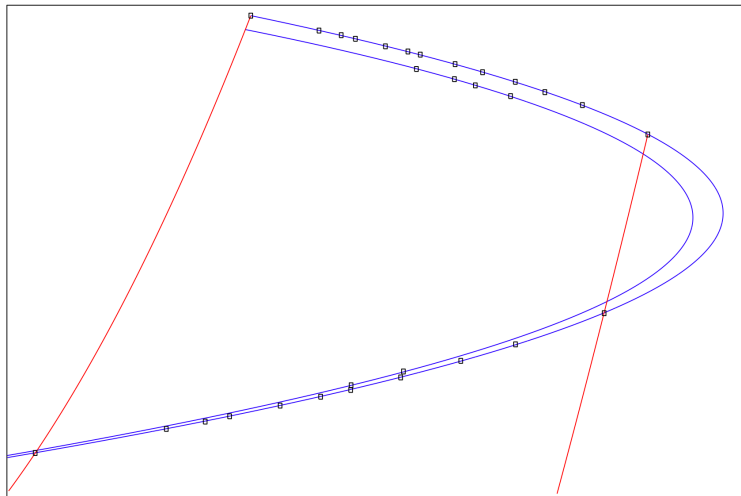
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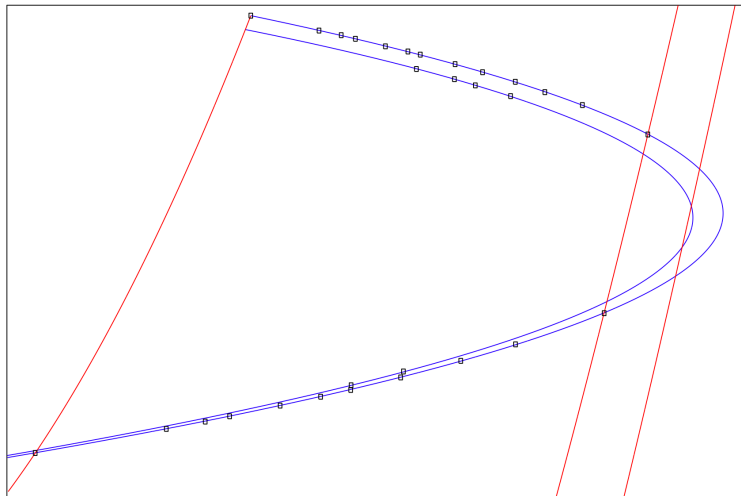
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$$\mathcal{H}^{-2}(S_1)$$



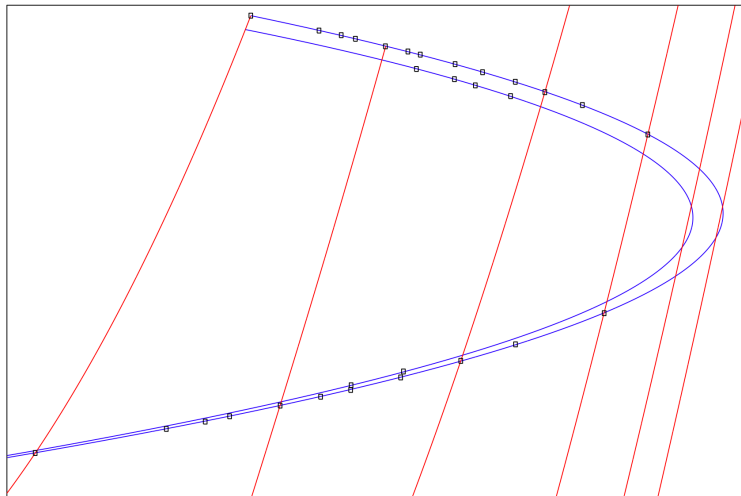
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$$\mathcal{H}^{-3}(S_1)$$



- └ Automatic determination of symbolic dynamics
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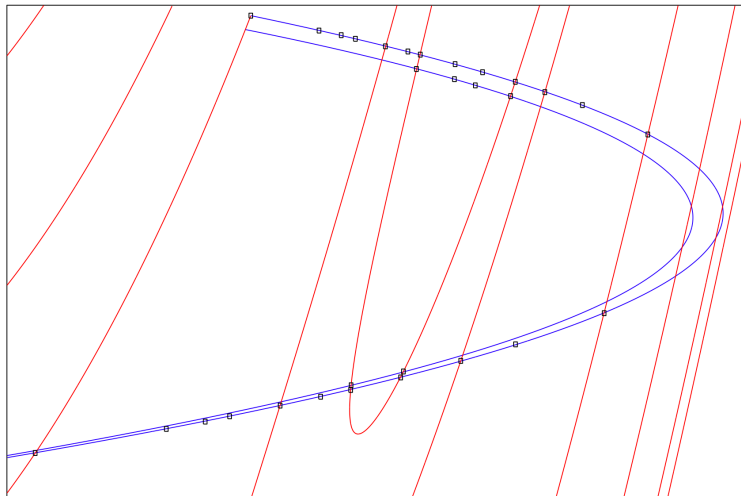
$$\mathcal{H}^{-4}(S_1)$$



└ Automatic determination of symbolic dynamics

└ Setup of incidence matrix

$$\mathcal{H}^{-5}(S_1)$$

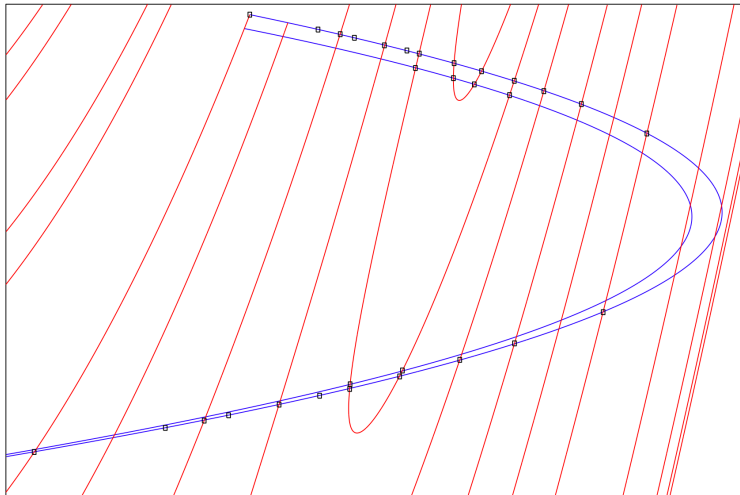




- └ Automatic determination of symbolic dynamics

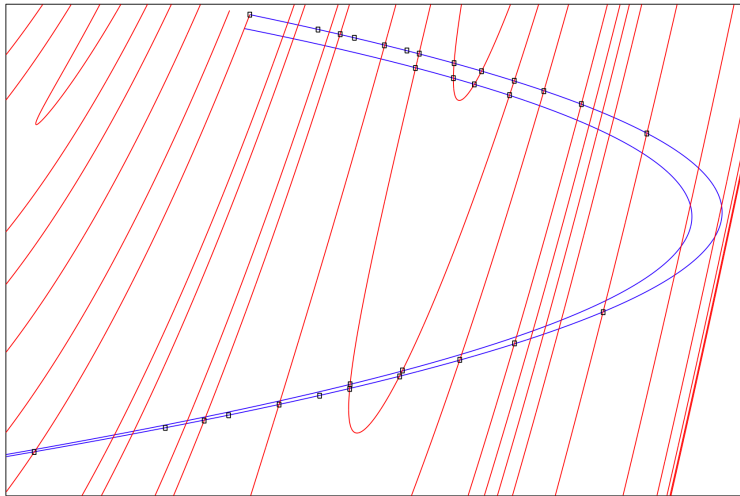
- └ Setup of incidence matrix

$$\mathcal{H}^{-6}(S_1)$$



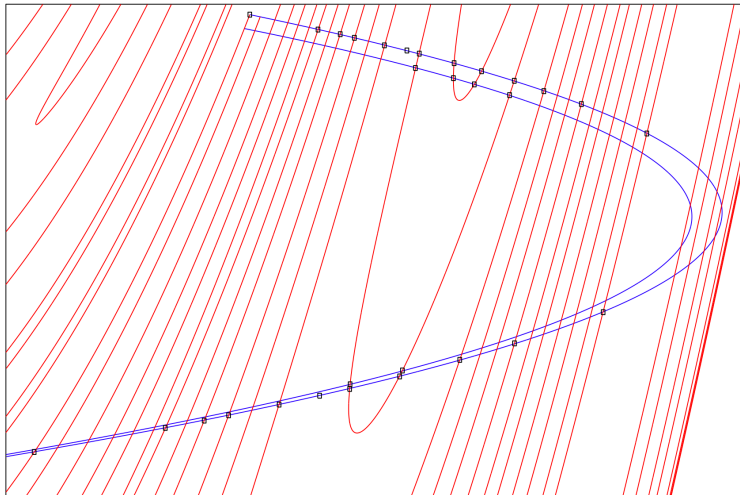
- └ Automatic determination of symbolic dynamics
- └ Setup of incidence matrix

$$\mathcal{H}^{-7}(S_1)$$



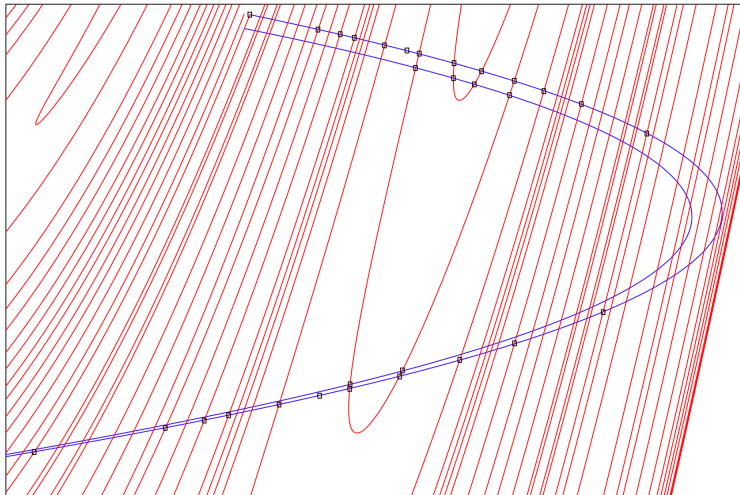
- └ Automatic determination of symbolic dynamics
- └ Setup of incidence matrix

$$\mathcal{H}^{-8}(S_1)$$



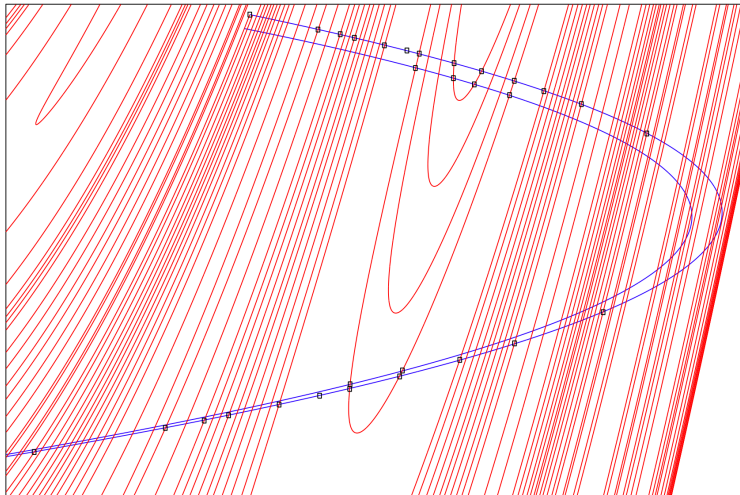
- └ Automatic determination of symbolic dynamics
- └ Setup of incidence matrix

$$\mathcal{H}^{-9}(S_1)$$



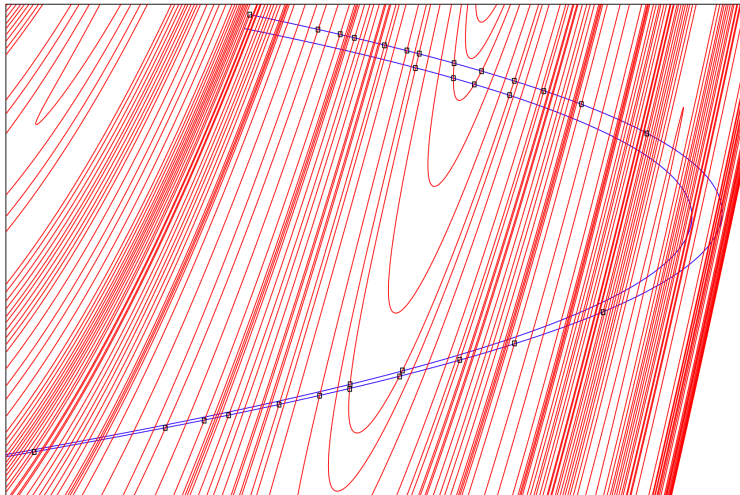
- └ Automatic determination of symbolic dynamics
- └ Setup of incidence matrix

$$\mathcal{H}^{-10}(S_1)$$



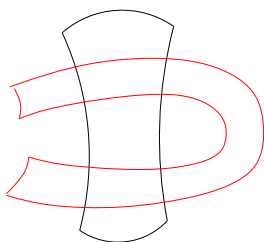
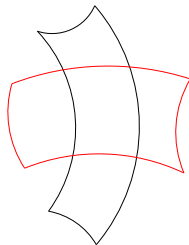
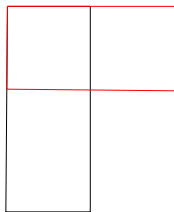
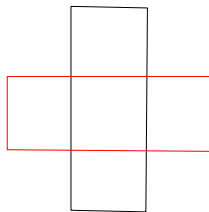
- └ Automatic determination of symbolic dynamics
- └ Setup of incidence matrix

$$\mathcal{H}^{-11}(S_1)$$



- └ Automatic determination of symbolic dynamics
- └ Setup of incidence matrix

## Examples for Markov crossings



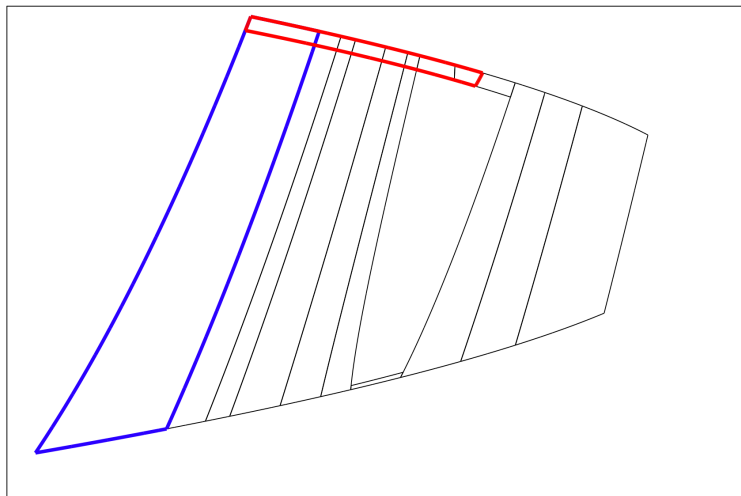
## Rectangle boundaries in $\mathcal{H}^{-n}(S_1)$

The first preimages of  $S_1$  where the rectangle boundaries occur:

<i>Rectangle</i>	$n_l$	$n_r$	<i>Rectangle</i>	$n_l$	$n_r$
$R_1$	0	8	$R_8$	5	4
$R_2$	8	6	$R_9$	4	6
$R_3$	6	8	$R_{10}$	6	3
$R_4$	8	4	$R_{11}$	5	6
$R_5$	4	11	$R_{12}$	6	6
$R_6$	11	5	$R_{13}$	6	5
$R_7$	5	5			

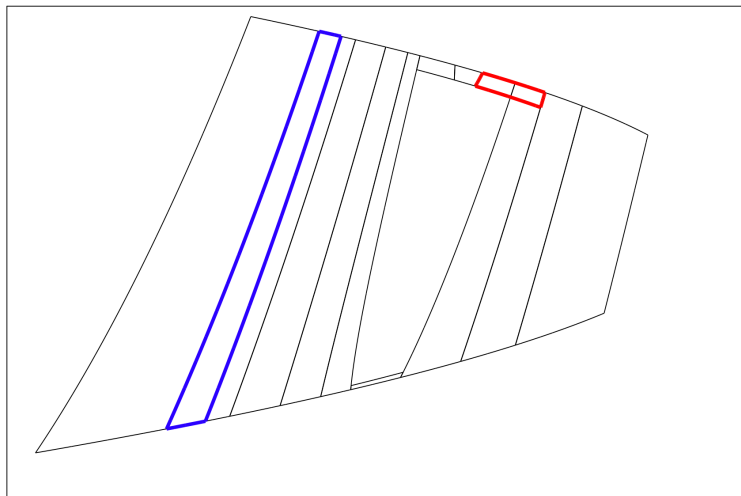


- └ Automatic determination of symbolic dynamics
- └ Verified mapping



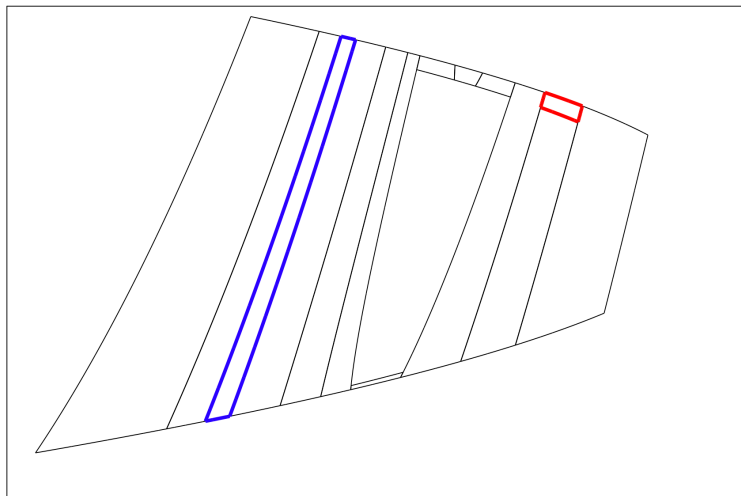
$$\mathcal{H}^2(R_1) \longrightarrow 1, 2, 3, 4, 5, 6, 11, 12$$

- └ Automatic determination of symbolic dynamics
- └ Verified mapping



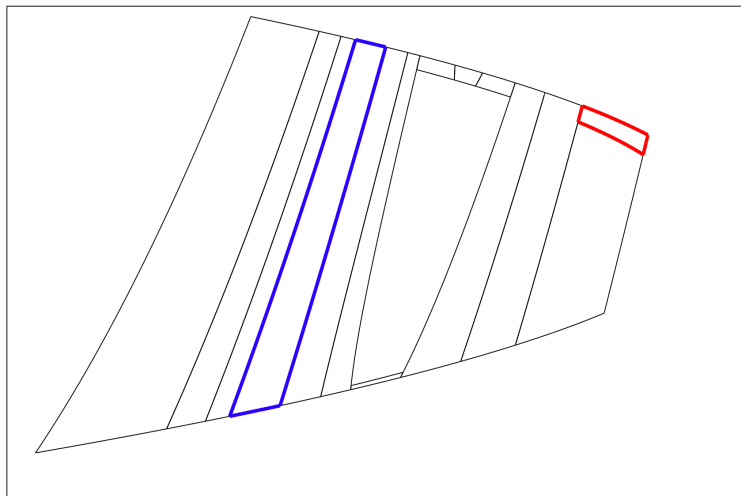
$$\mathcal{H}^2(R_2) \longrightarrow 13, 8$$

- └ Automatic determination of symbolic dynamics
- └ Verified mapping



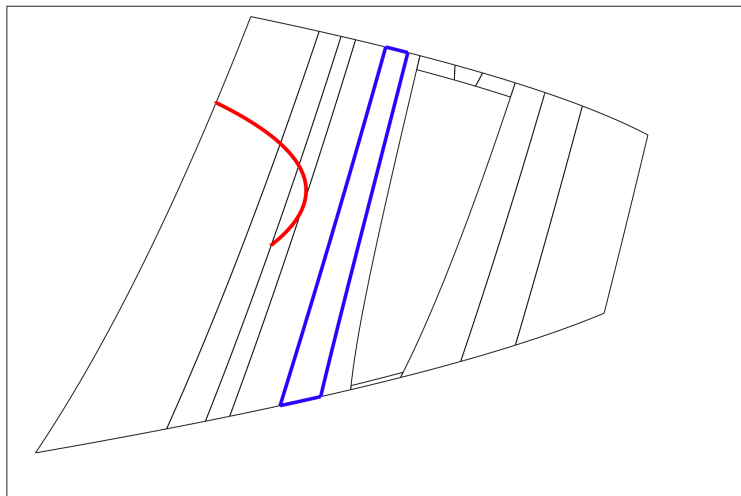
$$\mathcal{H}^2(R_3) \longrightarrow 9$$

- └ Automatic determination of symbolic dynamics
- └ Verified mapping



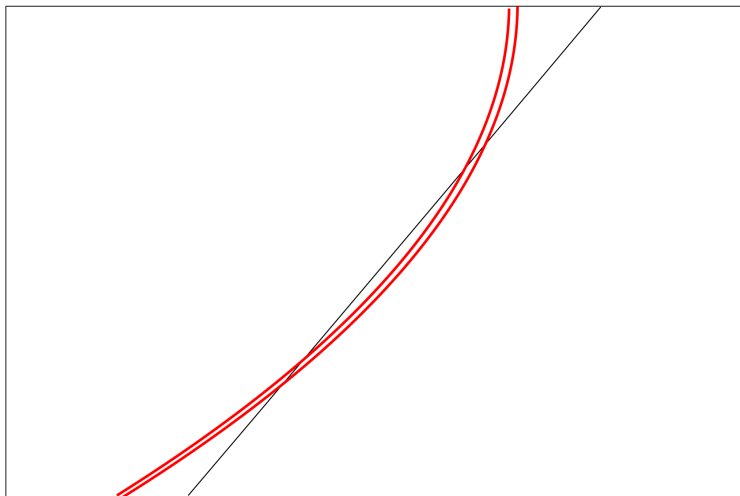
$$\mathcal{H}^2(R_4) \longrightarrow 10$$

- └ Automatic determination of symbolic dynamics
- └ Verified mapping



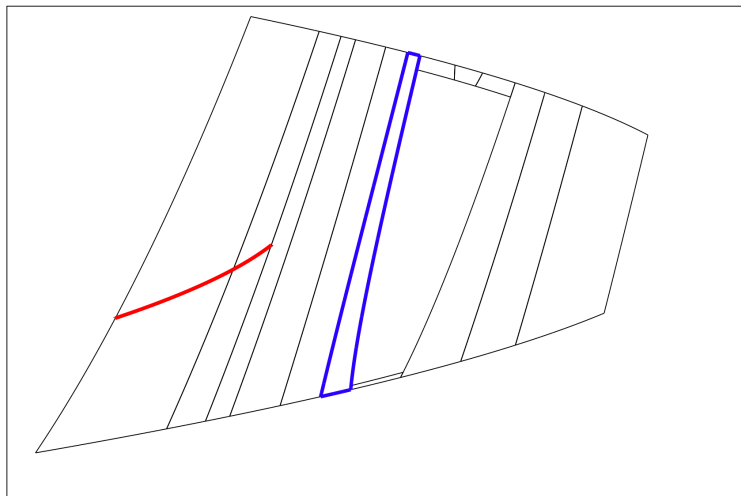
$$\mathcal{H}^5(R_5) \longrightarrow 1, 2, 3 \text{ (twice)}$$

- └ Automatic determination of symbolic dynamics
- └ Verified mapping



Close-up of  $\mathcal{H}^5(R_5) \cap R_3$

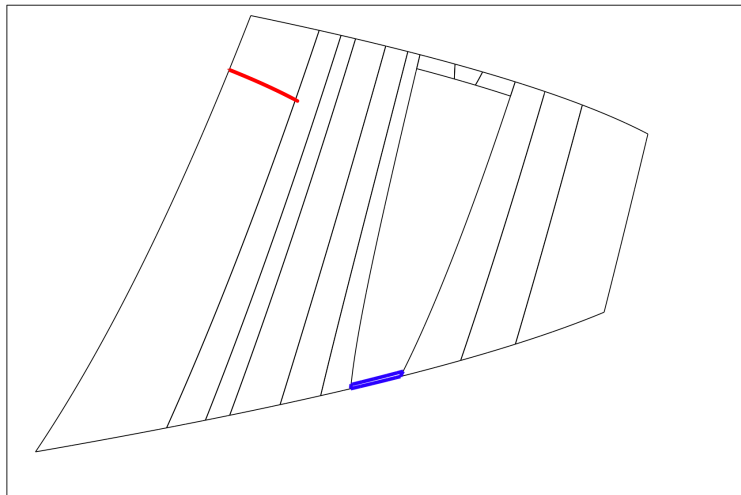
- └ Automatic determination of symbolic dynamics
- └ Verified mapping



$$\mathcal{H}^5(R_6) \longrightarrow 1, 2$$

## Rigorous Classification of Manifold Tangles and Bounds for Entropy

- └ Automatic determination of symbolic dynamics
- └ Verified mapping

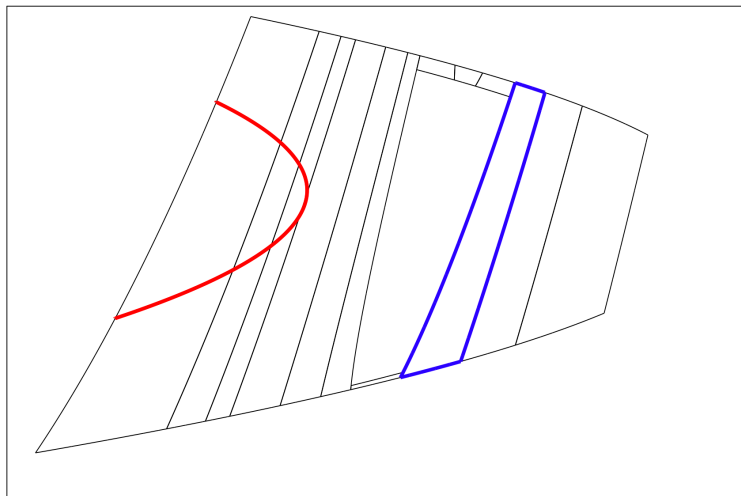


$$\mathcal{H}^6(R_7) \longrightarrow 1 \text{ (twice)}$$

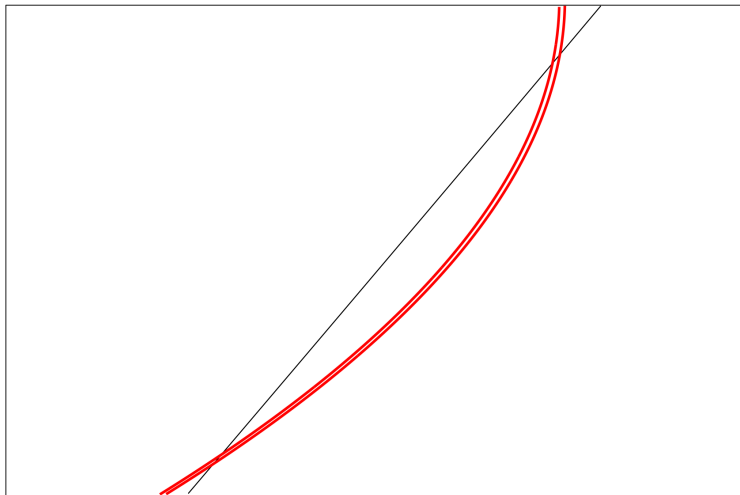


## Rigorous Classification of Manifold Tangles and Bounds for Entropy

- └ Automatic determination of symbolic dynamics
- └ Verified mapping

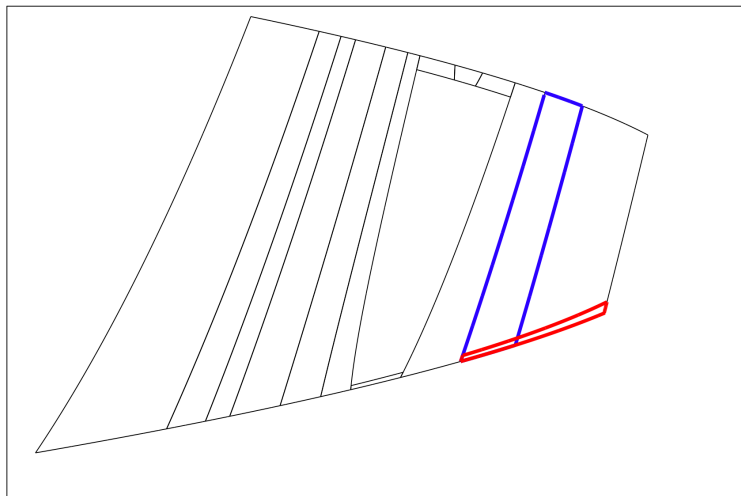


$$\mathcal{H}^5(R_8) \longrightarrow 1, 2, 3 \text{ (all twice)}$$



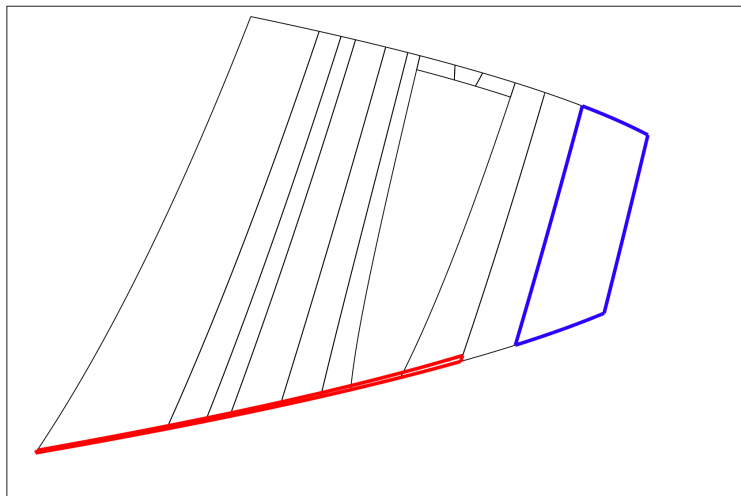
Close-up of  $\mathcal{H}^5(R_8) \cap R_3$

- └ Automatic determination of symbolic dynamics
- └ Verified mapping



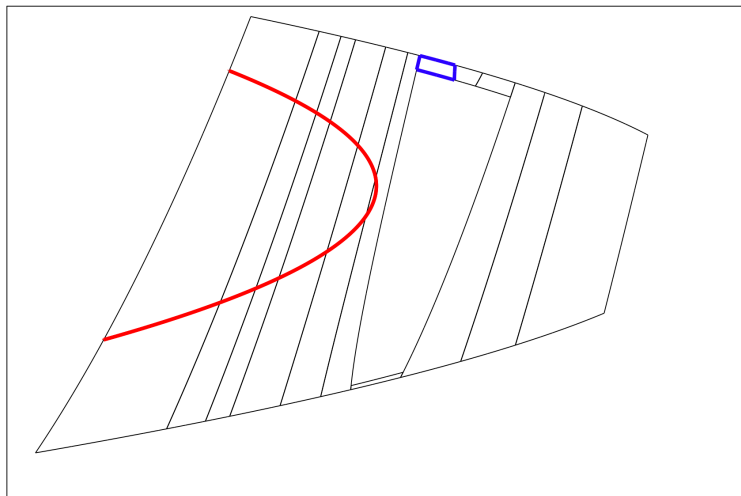
$$\mathcal{H}^2(R_9) \longrightarrow 9, 10$$

- └ Automatic determination of symbolic dynamics
- └ Verified mapping



$$\mathcal{H}^2(R_{10}) \longrightarrow 1, 2, 3, 4, 5, 6, 7, 8$$

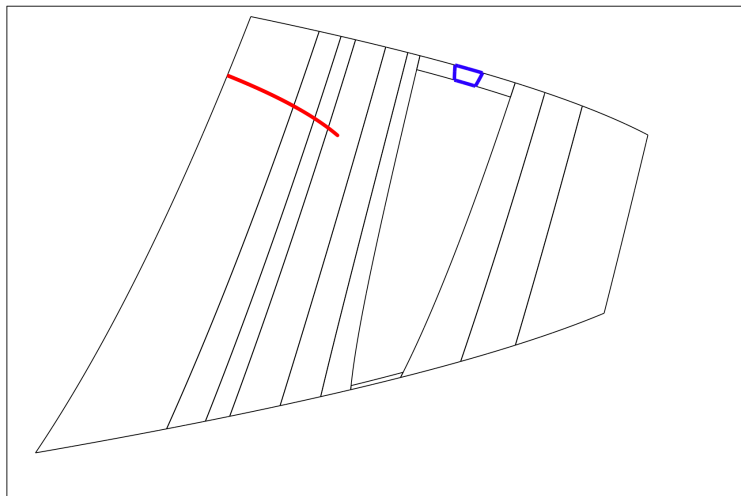
- └ Automatic determination of symbolic dynamics
- └ Verified mapping



$$\mathcal{H}^6(R_{11}) \longrightarrow 1, 2, 3, 4, 5 \text{ (all twice)}$$

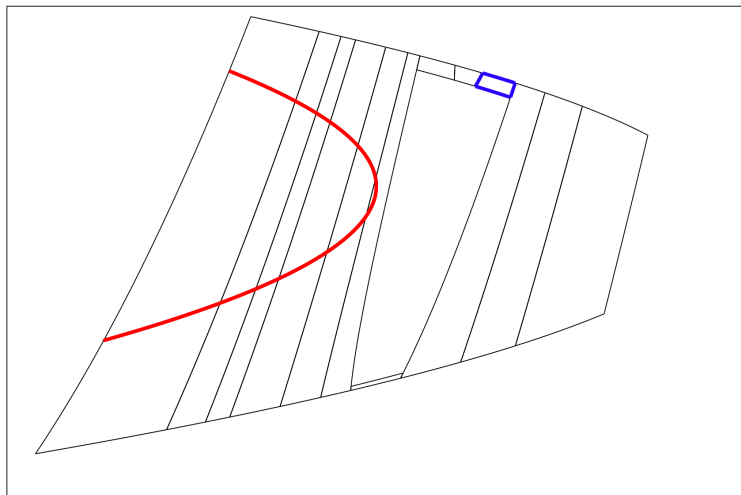
## Rigorous Classification of Manifold Tangles and Bounds for Entropy

- └ Automatic determination of symbolic dynamics
- └ Verified mapping



$$\mathcal{H}^7(R_{12}) \longrightarrow 1, 2, 3 \text{ (all twice)}$$

- └ Automatic determination of symbolic dynamics
- └ Verified mapping



$$\mathcal{H}^6(R_{13}) \longrightarrow 1, 2, 3, 4, 5 \text{ (all twice)}$$