

# On the Blunting Method in Verified Integration of ODEs

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(joint work with Ken Jackson and Ned Nedialkov)

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# Outline

- 1 Verified Integration of IVPs
- 2 Taylor Method for Model Problem
- 3 Wrapping Effect
- 4 The Blunting Method

# Verified Integration of IVPs

Interval IVP:

$$u' = f(t, u), \quad u(t_0) \in \mathbf{u}_0, \quad t \in \mathbf{t} = [t_0, t_{\text{end}}]$$

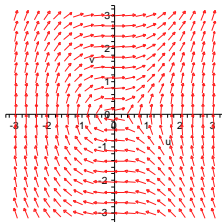
$f : \mathbb{R} \times \mathbb{R}^m \rightarrow \mathbb{R}^m$  sufficiently smooth,  $\mathbf{u}_0 \in \mathbb{IR}^m$ ,  $t_{\text{end}} > t_0$ .

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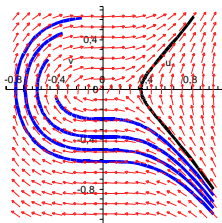


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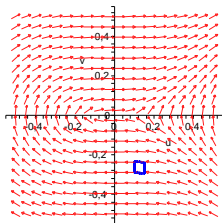


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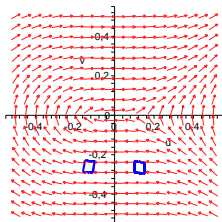


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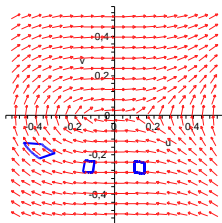


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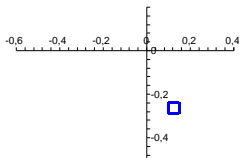


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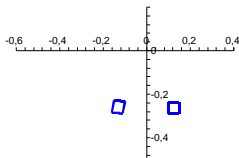


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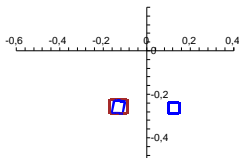


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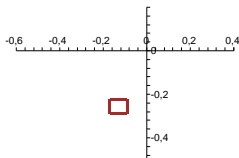


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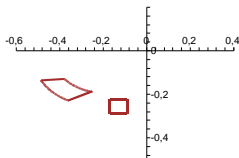


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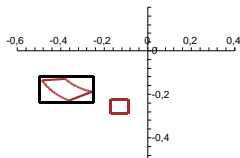


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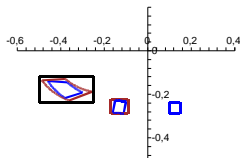


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## Enclosure Methods for ODEs

Convex sets used to enclose the flow:

Moore (1965):

Intervals

Eijgenraam (1981), Lohner (1987):

Parallelepipeds

Kühn (1998):

Zonotopes

Non-convex sets:

Berz & Makino (1996-):

Taylor models



## Interval Methods: Enclosure Representation

$$\begin{aligned}
 u(t_j; \mathbf{u}_0) &= \{u(t_j; u_0) \mid u_0 \in \mathbf{u}_0\} \\
 &\subseteq \{u_j + S_j w + B_j r \mid w \in \mathbf{u}_0 - m(\mathbf{u}_0), r \in \mathbf{r}_j\},
 \end{aligned}$$

where

- $u_j, w, r \in \mathbb{R}^m$ ,  $\mathbf{r}_j \in \mathbb{IR}^m$ ,
- $S_j, B_j \in \mathbb{R}^{m \times m}$ ,  $B_j$  nonsingular,
- $\{u_j + S_j w \mid w \in \mathbf{u}_0 - m(\mathbf{u}_0)\}$ : approximation to  $u(t_j; \mathbf{u}_0)$ ,
- $\{B_j r \mid r \in \mathbf{r}_j\}$ : bound on global error.

$$j = 0: \quad u_0 = m(\mathbf{u}_0), \quad \mathbf{r}_0 = 0, \quad S_0 = B_0 = I.$$

# Taylor Method for Model Problem

Model problem:

$$u' = Au, \quad (A \in \mathbb{R}^{m \times m}, m \geq 2)$$

$$u(0) = u_0 \in \mathbf{u}_0.$$

Taylor method (constant order  $n$ , stepsize  $h$ ):

$$u_j := Tu_{j-1} \quad , \quad j = 1, 2, \dots$$

$$\left( T = T_{n-1}(hA) = \sum_{\nu=0}^{n-1} \frac{(hA)^\nu}{\nu!} \right)$$

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$$u_j := Tu_{j-1} + z_j, \quad j = 1, 2, \dots$$

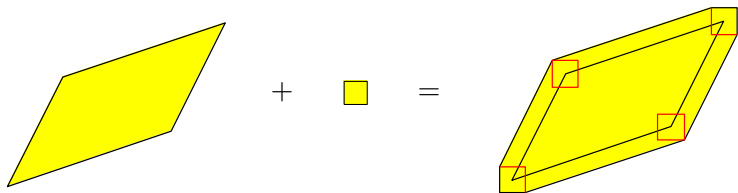
$$\left( T = T_{n-1}(hA) = \sum_{\nu=0}^{n-1} \frac{(hA)^\nu}{\nu!}; \quad z_j : \text{local error} \right)$$

## Propagation of the Global Error

$$\mathbf{r}_j = (B_j^{-1} T B_{j-1}) \mathbf{r}_{j-1} + B_j^{-1} (\mathbf{z}_j - m(\mathbf{z}_j)).$$

Required:  $B_j$  for tight enclosure:

$$\{TB_{j-1}r + z \mid r \in \mathbf{r}_{j-1}, z \in \mathbf{z}_j - m(\mathbf{z}_j)\} \subseteq \{B_j r \mid r \in \mathbf{r}_j\}.$$

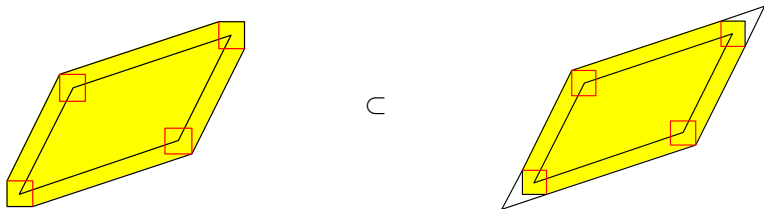


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- Direct method:  $B_j = I.$
- Parallelepiped (P) method:  $B_j = T B_{j-1}.$
- QR method:  $B_j = Q_j, Q_j R_j = T B_{j-1}.$
- Blunting (B) method:  $B_j = T B_{j-1} + \varepsilon Q_j, \varepsilon > 0.$

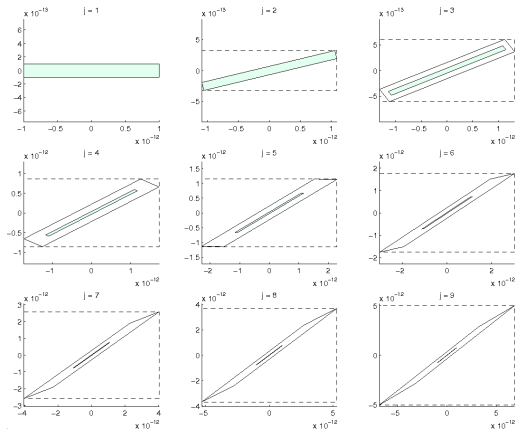
## Wrapping Effect: Direct Method

$$\mathbf{r}_j = (B_j^{-1} T B_{j-1}) \mathbf{r}_{j-1} + B_j^{-1} (\mathbf{z}_j - m(\mathbf{z}_j)), \quad B_j = I :$$

$$\mathbf{r}_j = T \mathbf{r}_{j-1} + \mathbf{z}_j - m(\mathbf{z}_j).$$

- Optimal coordinates for local error.
- Bad coordinates for global error (rotation).

# Wrapping Effect: Direct Method



Huge overestimations in general.



## Wrapping Effect: P Method

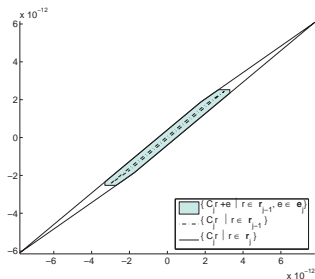
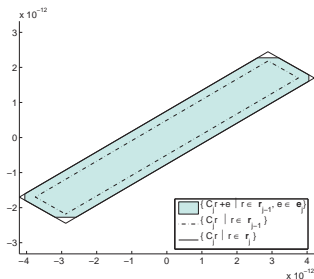
$$\mathbf{r}_j = (B_j^{-1} T B_{j-1}) \mathbf{r}_{j-1} + B_j^{-1} (\mathbf{z}_j - \mathbf{m}(\mathbf{z}_j)), \quad B_j = T B_{j-1} :$$

$$\mathbf{r}_j = \mathbf{r}_{j-1} + T^{-j} (\mathbf{z}_j - \mathbf{m}(\mathbf{z}_j)).$$

- Optimal coordinates for global error.
- Suitable coordinates for local error, if  $\text{cond}(T^j)$  is small.
- Bad coordinates for local error in presence of shear ( $T^j$  becomes singular for  $j \rightarrow \infty$ ).

# Wrapping Effect: P Method

$$B_j = TB_{j-1}$$



$B_j$  often ill-conditioned, large overestimations.

## Wrapping Effect: QR Method

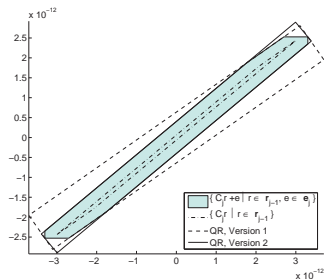
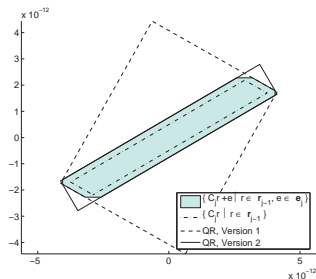
$$\mathbf{r}_j = (B_j^{-1}TB_{j-1})\mathbf{r}_{j-1} + B_j^{-1}(\mathbf{z}_j - m(\mathbf{z}_j)), \quad B_j = Q_j, \quad Q_jR_j = TB_{j-1} :$$

$$\mathbf{r}_j = R_j\mathbf{r}_{j-1} + Q_j^T(\mathbf{z}_j - m(\mathbf{z}_j)).$$

- Suitable, but not optimal coordinates for global error.
- Kühn: Numerical example for exponential overestimation.
- Good coordinates for local error.
- Handles rotation, contraction, shear.

# Wrapping Effect: QR Method

$$B_j = Q_j, \quad Q_j R_j = T B_{j-1}$$



Overestimation depends on column permutations of  $B_{j-1}$ .

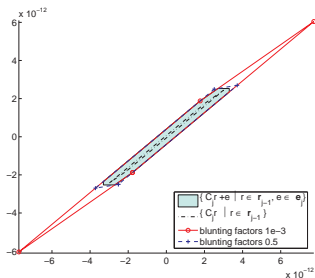
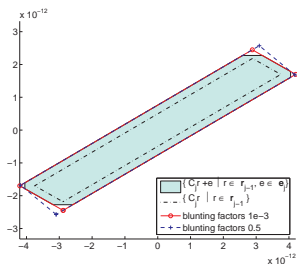
## Wrapping Effect: B Method

$$\mathbf{r}_j = (B_j^{-1}TB_{j-1})\mathbf{r}_{j-1} + B_j^{-1}(\mathbf{z}_j - m(\mathbf{z}_j)), \quad B_j = TB_{j-1} + \varepsilon Q_j.$$

- Coordinates for global error sometimes better than QR.
- Sometimes worse?
- Suitable coordinates for local error.
- Handles rotation, contraction, shear.

# Wrapping Effect: B Method

$$B_j = TB_{j-1} + \varepsilon Q_j, \varepsilon > 0.$$



Overestimation depends on blunting factors.

## Propagation of the Global Error

Global error:

$$\mathbf{r}_j = (B_j^{-1}TB_{j-1})\mathbf{r}_{j-1} + B_j^{-1}(\mathbf{z}_j - m(\mathbf{z}_j)),$$

$$w(\mathbf{r}_j) = |B_j^{-1}TB_{j-1}|w(\mathbf{r}_{j-1}) + |B_j^{-1}|w(\mathbf{z}_j).$$

QR method (Nedialkov & Jackson 2001): Error propagation depends on spectral radius of

$$H_j = |Q_j^{-1}TQ_{j-1}| |Q_{j-1}^{-1}TQ_{j-2}| \cdots |Q_2^{-1}TQ_1|.$$

B method: Error propagation depends on spectral radius of

$$P_j = |B_j^{-1}TB_{j-1}| |B_{j-1}^{-1}TB_{j-2}| \cdots |B_2^{-1}TB_1|.$$

## Propagation of the Global Error

Assume:  $T$  has eigenvalues  $\lambda_j$  of distinct magnitudes:

$$|\lambda_1| > |\lambda_2| > \dots > |\lambda_n| > 0.$$

QR method:  $\text{diag}(H_j) \rightarrow (|\lambda_1|^j, |\lambda_2|^j, \dots, |\lambda_n|^j)$ .  $(j \rightarrow \infty)$

B method:  $\text{diag}(P_j) \rightarrow (|\lambda_1|^j, \alpha_2 |\lambda_2|^j, \dots, \alpha_n |\lambda_n|^j)$ ,

where

$$\frac{\varepsilon}{1 + \varepsilon} \leq \alpha_k \leq 1 + \frac{1}{\varepsilon}.$$

$$\varepsilon = 10^{-3}: \quad 10^{-3} \approx \frac{10^{-3}}{1 + 10^{-3}} \leq \alpha_k \leq 1001.$$

$$\varepsilon = 1: \quad 0.5 \leq \alpha_k \leq 2.$$

Similar error propagation if  $|\alpha_k| \approx 1$  for  $k = 2, \dots, n$ .



## Condition number of $B_j$

B method:  $B_j = Q_j V_j$ ,  $Q_j$  orthogonal:

$$\|V_j^{-1}\|_{1,\infty} \leq \frac{(1 + 1/\varepsilon)^{n-1}}{\varepsilon}.$$

$$\varepsilon = 10^{-3}: \quad \|V_j^{-1}\|_{1,\infty} \leq 10^3(10^3 + 1)^{n-1}.$$

$$\varepsilon = 1: \quad \|V_j^{-1}\|_{1,\infty} \leq 2^{n-1}.$$

## Open Problems

- Optimal choice of blunting factors  
( $D_j = \text{diag}(\varepsilon_1, \dots, \varepsilon_n)$ ).
- Quality of upper bounds for  $\text{cond}(B_j)$ .
- $T$  with eigenvalues of same magnitude.
- Column permutations of  $B_j$ .

Thank you.

Questions or Remarks?